

# Mixing, stopping, coupling, lifting, and other keys to the second Markov-chain revolution

Werner Krauth

Department of Physics, Ecole normale supérieure  
Paris, France

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# Plan of talk

- ➊ Introduction (+ Example I)
- ➋ Mixing and Relaxing (+ Example II)
- ➌ Stopping and Coupling (+ Example III)
- ➍ Equilibrium out of Equilibrium (+ Example IV)
- ➎ Conclusion

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## Equation of State Calculations by Fast Computing Machines

NICHOLAS METROPOLIS, ARIANNA W. ROSENBLUTH, MARSHALL N. ROSENBLUTH, AND AUGUSTA H. TELLER,  
*Los Alamos Scientific Laboratory, Los Alamos, New Mexico*

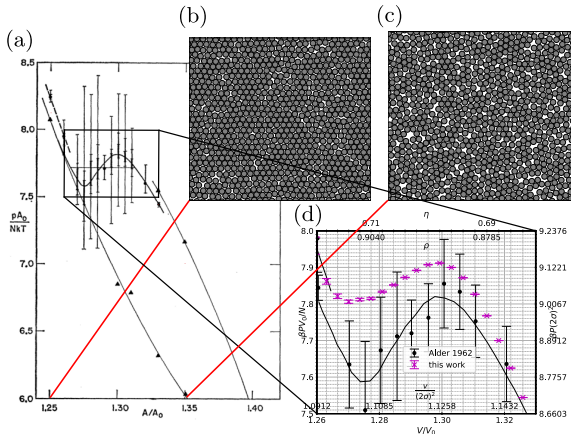
AND

EDWARD TELLER,\* *Department of Physics, University of Chicago, Chicago, Illinois*  
(Received March 6, 1953)

A general method, suitable for fast computing machines, for investigating such properties as equations of state for substances consisting of interacting individual molecules is described. The method consists of a modified Monte Carlo integration over configuration space. Results for the two-dimensional rigid-sphere system have been obtained on the Los Alamos MANIAC and are presented here. These results are compared to the free volume equation of state and to a four-term virial coefficient expansion.



# Example I: Equilibrated (?) samples



- Original figure from Alder & Wainwright 1962, see Li et al. (2022)

# Markov chains (2/2)

- **Sample space  $\Omega$**  (e.g. hard disks, water molecules, quarks, ...)
- **Markov chain**  $\leftarrow$  Sequence of random variables  
( $X_0 \sim \pi^{\{0\}}, X_1 \sim \pi^{\{1\}}, X_2 \sim \pi^{\{2\}} \dots$ )  
 $X_{t+1}$  depends only on  $X_t$ ,  $t$  is a 'time'
- **Transition matrix  $P$ :**
  - $P_{ij}$ : conditional probability to move from sample  $i$  to sample  $j$ .
  - $\pi^{\{t+1\}} = \pi^{\{t\}} P$ : Evolve probability distribution at time  $t$  to probability distribution at time  $t + 1$  (with  $\pi^{\{t\}}, t > 0$  often non-explicit, even for  $t \rightarrow \infty$ ).
- **Move set  $\mathcal{L}$ :** ... from which moves are sampled.
- **Equilibrium distribution  $\pi$ :** Satisfies global balance:

$$\pi_i = \sum_{j \in \Omega} \pi_j P_{ji} \quad \forall i \in \Omega.$$

NB:  $P$  irreducible  $\implies \pi$  unique.

- **Aperiodicity:** Absence of cycles.  $P$  irreducible and aperiodic:

$$\pi^{\{t\}} \rightarrow \pi \quad \text{for } t \rightarrow \infty$$

# Total variation distance, mixing time

- Total variation distance:

$$\|\pi^{\{t\}} - \pi\|_{\text{TV}} = \max_{A \subset \Omega} |\pi^{\{t\}}(A) - \pi(A)| = \frac{1}{2} \sum_{i \in \Omega} |\pi_i^{\{t\}} - \pi_i|.$$

- Distance:

$$d(t) = \max_{\pi^{\{0\}}} \|\pi^{\{t\}}(\pi^{\{0\}}) - \pi\|_{\text{TV}}$$

- Mixing time:

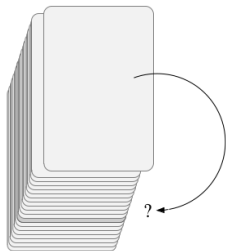
$$t_{\text{mix}}(\epsilon) = \min\{t : d(t) \leq \epsilon\}$$

- Usually  $\epsilon = 1/4$  is taken,  $\epsilon = 1/e$  would be better.

# Plan of talk

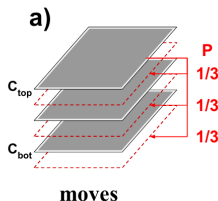
- 1 Introduction
- 2 **Mixing and Relaxing**
- 3 Stopping and Coupling
- 4 Equilibrium out of Equilibrium
- 5 Conclusion

# Shuffling of cards 1/5



- $\Omega_N^{\text{shuffle}} = \{\text{Permutations of } \{1, \dots, N\}\}$
- For  $N = 3$ :  
 $\Omega_3^{\text{shuffle}} = \{1 \equiv \{1, 2, 3\}, 2 \equiv \{1, 3, 2\}, 3 \equiv \{2, 1, 3\}, 4 \equiv \{2, 3, 1\}, 5 \equiv \{3, 1, 2\}, 6 \equiv \{3, 2, 1\}\}.$
- $\pi^{t=0} = \delta((1, \dots, N))$

# Shuffling of cards 2/5



**procedure** top-to-random

**input**  $\{c_1, \dots, c_n\}$

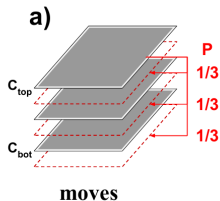
$i \leftarrow \text{choice}(\{1, \dots, n\})$

$\{\hat{c}_1, \dots, \hat{c}_n\} \leftarrow \{c_2, \dots, c_i, c_1, c_{i+1}, \dots, c_n\}$

**output**  $\{\hat{c}_1, \dots, \hat{c}_n\}$

- Insert upper card ( $c_1$ ) after card  $i$  and before card  $i + 1$
- NB: if  $i = 1$ , put it back on top.

# Shuffling of cards 3/5



- $\Omega_3^{\text{shuffle}} = \{1 \equiv \{1, 2, 3\}, 2 \equiv \{1, 3, 2\}, 3 \equiv \{2, 1, 3\}, 4 \equiv \{2, 3, 1\}, 5 \equiv \{3, 1, 2\}, 6 \equiv \{3, 2, 1\}\}.$

•

$$P = \frac{1}{3} \begin{pmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 & 1 \end{pmatrix}$$

# Shuffling of cards 4/5



$$P_3^{\text{shuffle}} = \frac{1}{3} \begin{pmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 & 1 \end{pmatrix}$$

- Eigenvalues of  $P_N^{\text{shuffle}}$ :  $0, \frac{1}{N}, \frac{2}{N}, \dots, 1 - \frac{2}{N}, 1$
- Degeneracies:

$$N = 2 : [1, 0, 1]$$

$$N = 3 : [2, 3, 0, 1]$$

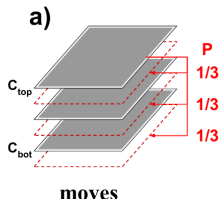
$$N = 4 : [9, 8, 6, 0, 1]$$

$$N = 5 : [44, 45, 20, 10, 0, 1]$$

$$N = 6 : [265, 264, 135, 40, 15, 0, 1]$$

$$N = 7 : [1854, 1855, 924, 315, 70, 21, 0, 1]$$

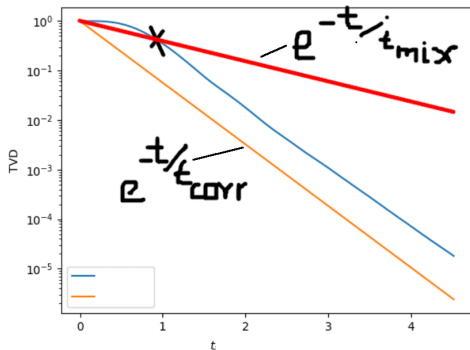
# Shuffling of cards 5/5



```
procedure top2random-stop
input  $\{c_1, \dots, c_n\}$ 
 $c_{\text{first-n}} \leftarrow c_n$ 
for  $t = 1, 2, \dots$  do
     $\tilde{c}_1 \leftarrow c_1$ 
     $\{c_1, \dots, c_n\} \leftarrow \text{top2random}(\{c_1, \dots, c_n\})$ 
    if  $(\tilde{c}_1 = c_{\text{first-n}})$  break
output  $\{c_1, \dots, c_n, t\}$ 
```

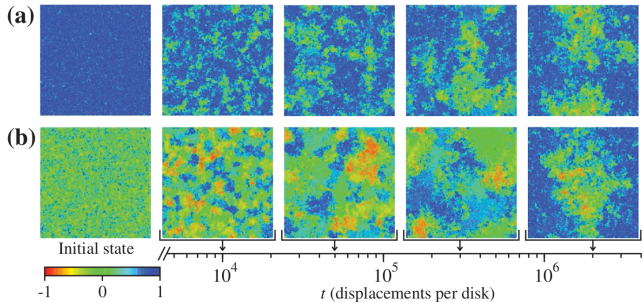
- Expected running time:  $n \log n$ .
- Time scale  $N \log N$  larger than inverse gap  $N/2$ .

# Mixing and Relaxation



- $t_{\text{mix}} = \|\pi^{\{t_{\text{mix}}\}} - \pi\|_{\text{TV}} = 1/e$ , (non-asymptotic time scale).
- $t_{\text{corr}}$  = inverse gap, (asymptotic time scale).
- $t_{\text{mix}} \gg t_{\text{corr}}$  leads to cutoff phenomenon.
- Aldous–Diaconis (1986)
- Diaconis–Fill–Pitman (1992)

## Example II: A non-asymptotic time scale

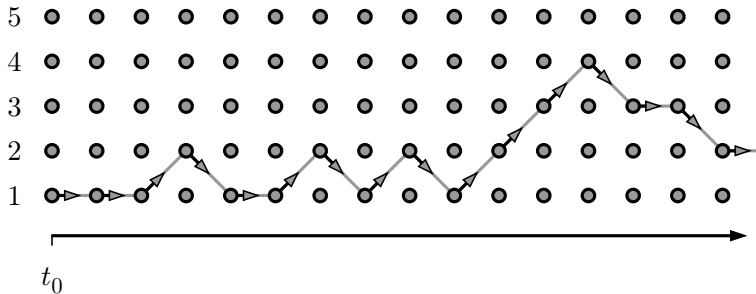


- Coarsening in hard disks (from Bernard & Krauth 2011)...
- ... an example of a non-asymptotic mixing-time scale

# Plan of talk

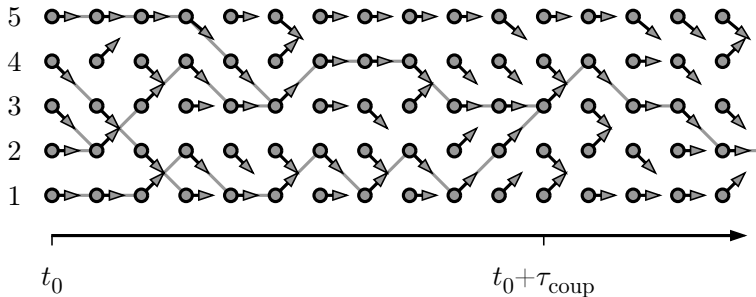
- ① Introduction
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# Markov chain



- Configuration  $c_t$ , move  $\delta_t$ .
- Set  $t_0 = 0$ .

# Markov chain (random maps), coupling 1/3



- Each configuration has its move at each time step.
- Coupling (Doeblin, 1930s).

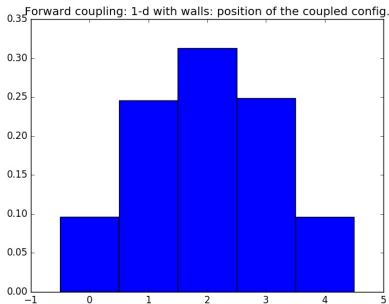
# Markov chain (random maps), coupling 2/3

```
procedure forward-coupling
 $\mathcal{P} \leftarrow \{1, \dots, N\}$ 
 $t \leftarrow 0$ 
while True:
     $t \leftarrow t + 1$ 
     $\mathcal{P} \leftarrow \{\min[\max(b + \text{choice}\{-1, +1\}, 1), N] \text{ for } b \in \mathcal{P}\}$ 
    if  $|\mathcal{P}| = 1$ : break
output  $\mathcal{P}, t$  (position, time of coupling)
```

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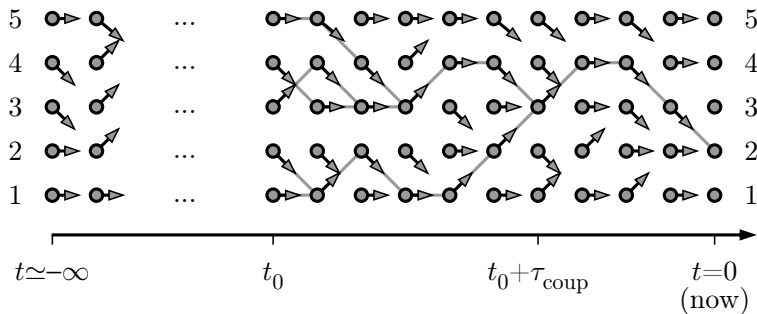
- Position of coupling not uniform.
- Coupling time larger than mixing time.

# Markov chain (random maps), coupling 3/3



- Histogram of coupling position.

# Coupling from the past 1/3



- Starting an MCMC simulation at  $t = -\infty$
- Propp & Wilson (1997)

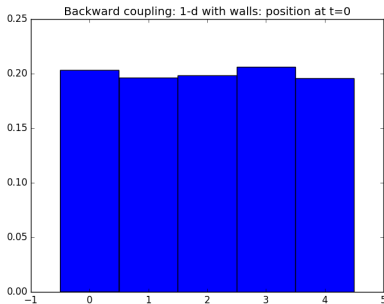
# Coupling from the past 2/3

```
procedure coupling-from-past
 $t_{\text{tot}} \leftarrow 0$ 
while True:
    {
         $t_{\text{tot}} \leftarrow t_{\text{tot}} - 1$ 
         $\mathcal{A}_{t_{\text{tot}}} \leftarrow \text{draw-arrows}$  (draw arrows at time  $t_{\text{tot}}$ )
         $\mathcal{P} \leftarrow \{1, \dots, N\}$ 
        for  $t = t_{\text{tot}}, t_{\text{tot}} + 1, \dots, -1$ :
            {  $\mathcal{P} \leftarrow \{b + \mathcal{A}_t(b) \text{ for } b \in \mathcal{P}\}$ 
            if  $|\mathcal{P}| = 1$ : break
        }
    }
output  $\mathcal{P}$  ((perfect) sample)
```

---

- Propp & Wilson (1997)

# Coupling from the past 3/3



- Propp & Wilson (1997)
- see `CouplingFromThePast.py` on my website

## Example III: Perfect Monte Carlo samples of hard disks

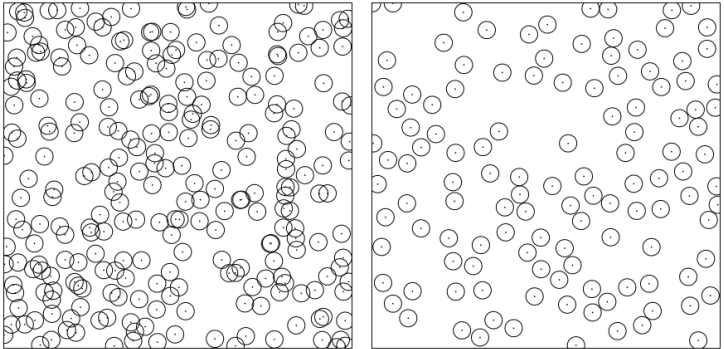


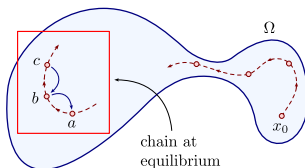
Figure 10: Perfectly random samples of the Strauss point process. In both panels the point

- Perfect sample of hard disks (right) from Wilson (2000)

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# Detailed balance, global balance, lifting



- Reversible transition matrices  $P$  satisfy the 'detailed-balance' condition:

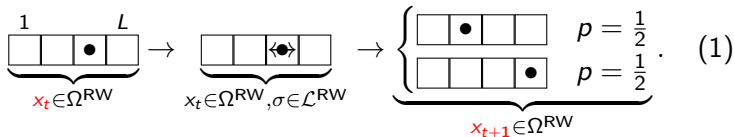
$$\pi_a P_{ab} = \pi_b P_{ba}$$

- Non-reversible transition matrices  $P$  only satisfy 'global balance':

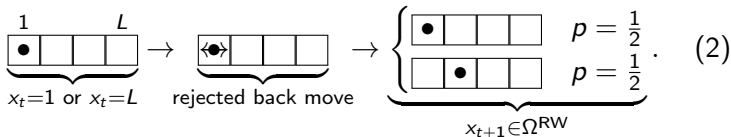
$$\pi_a = \sum_{b \in \Omega} \pi_b P_{ba}$$

# Random walk (RW) on the one-dimensional lattice

- In the bulk:



- At the boundary:



# Lifted random walk (L-RW)

- Lifting of samples:

$$\underbrace{\begin{array}{|c|c|c|c|} \hline & & \bullet & \\ \hline \end{array}}_{x_t \in \Omega^{RW}} \xrightarrow{i} \left\{ \begin{array}{|c|c|c|c|} \hline & & \bullet \rightarrow & \\ \hline & & \leftarrow \bullet & \\ \hline \end{array} \right\}_{x_t \in \Omega^{L-RW}}^{(i, \sigma)} \quad (3)$$

- In the bulk:

$$\underbrace{\begin{array}{|c|c|c|c|} \hline & & \bullet & \\ \hline \end{array}}_{x_t \in \Omega^{L-RW}} \xrightarrow{p=1} \begin{array}{|c|c|c|c|} \hline & & \bullet & \\ \hline \end{array} \xrightarrow{i+\sigma} \left\{ \begin{array}{|c|c|c|c|} \hline & \bullet \rightarrow & & \\ \hline & \leftarrow \bullet & & \\ \hline \end{array} \right\}_{x_{t+1} \in \Omega^{L-RW}, \alpha \ll 1, \beta = 1 - \alpha} \begin{array}{l} p = \alpha \\ p = \beta \end{array} \quad (4)$$

- At the boundary:

$$\underbrace{\begin{array}{|c|c|c|c|} \hline \leftarrow \bullet & & & \\ \hline \end{array}}_{x_t \text{ at end point}} \xrightarrow{p=1} \underbrace{\begin{array}{|c|c|c|c|} \hline \bullet \rightarrow & & & \\ \hline \end{array}}_{\sigma \rightarrow -\sigma} \xrightarrow{} \left\{ \begin{array}{|c|c|c|c|} \hline \leftarrow \bullet & & & \\ \hline \bullet \rightarrow & & & \\ \hline \end{array} \right\}_{x_{t+1} \in \Omega^{L-RW}} \begin{array}{l} p = \alpha \\ p = \beta \end{array} \quad (5)$$

# Random walk, lifted random walk (examples)

•  $1 \equiv \begin{array}{|c|c|c|c|} \hline \bullet & & & \\ \hline \end{array}$      $2 \equiv \begin{array}{|c|c|c|c|} \hline & \bullet & & \\ \hline \end{array}$      $3 \equiv \begin{array}{|c|c|c|c|} \hline & & \bullet & \\ \hline \end{array}$      $4 \equiv \begin{array}{|c|c|c|c|} \hline & & & \bullet \\ \hline \end{array}$

$$P_{\text{walls}}^{RW} = \frac{1}{2} \begin{bmatrix} 1 & 1 & \cdot & \cdot \\ 1 & \cdot & 1 & \cdot \\ \cdot & 1 & \cdot & 1 \\ \cdot & \cdot & 1 & 1 \end{bmatrix}$$

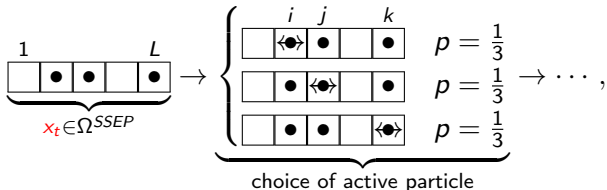
• Lifted random walk (NB:  $\alpha + \beta = 1$ ,  $\alpha \sim 1/L$ )

$1 \equiv \begin{array}{|c|c|c|c|} \hline \bullet \rightarrow & & & \\ \hline \end{array}$      $3 \equiv \begin{array}{|c|c|c|c|} \hline & \bullet \rightarrow & & \\ \hline \end{array}$      $5 \equiv \begin{array}{|c|c|c|c|} \hline & & \bullet \rightarrow & \\ \hline \end{array}$      $7 \equiv \begin{array}{|c|c|c|c|} \hline & & & \bullet \rightarrow \\ \hline \end{array}$   
 $2 \equiv \begin{array}{|c|c|c|c|} \hline \bullet \leftarrow & & & \\ \hline \end{array}$      $4 \equiv \begin{array}{|c|c|c|c|} \hline & \bullet \leftarrow & & \\ \hline \end{array}$      $6 \equiv \begin{array}{|c|c|c|c|} \hline & & \bullet \leftarrow & \\ \hline \end{array}$      $8 \equiv \begin{array}{|c|c|c|c|} \hline & & & \bullet \leftarrow \\ \hline \end{array}$

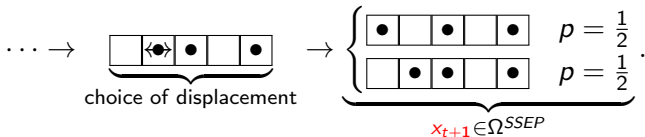
$$P_{\text{walls}}^{LRW} = \begin{bmatrix} \boxed{\begin{matrix} \cdot & \cdot \\ \beta & \alpha \end{matrix}} & \boxed{\begin{matrix} \beta & \alpha \\ \cdot & \cdot \end{matrix}} & \cdot & \cdot & \cdot & \cdot \\ \boxed{\begin{matrix} \cdot & \cdot \\ \alpha & \beta \end{matrix}} & \cdot & \cdot & \boxed{\begin{matrix} \beta & \alpha \\ \cdot & \cdot \end{matrix}} & \cdot & \cdot \\ \cdot & \cdot & \boxed{\begin{matrix} \cdot & \cdot \\ \alpha & \beta \end{matrix}} & \cdot & \cdot & \boxed{\begin{matrix} \beta & \alpha \\ \cdot & \cdot \end{matrix}} \\ \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \cdot & \cdot \\ \alpha & \beta \end{matrix}} & \boxed{\begin{matrix} \beta & \alpha \\ \alpha & \beta \end{matrix}} \end{bmatrix},$$

# Symmetric simple exclusion process (SSEP)

- Move (first part ...)

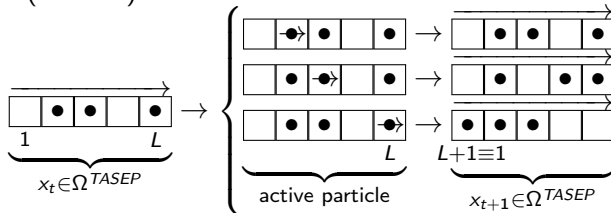


- Move (... second part)

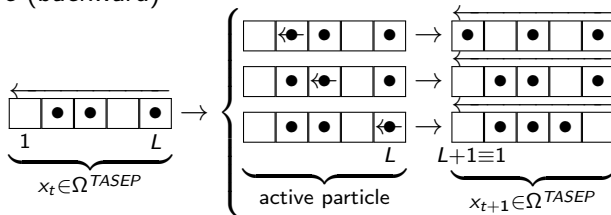


# Totally asymmetric simple exclusion process (TASEP)

- Move (forward)



- Move (backward)



- forward-backward coupling (ad-hoc, or boundary conditions).

NB: Non-reversible, i.e. non-equilibrium, but samples equilibrium Boltzmann distribution.

# Lifted TASEP (definition)

- $\Omega^{l-TASEP} = \Omega^{SSEP} \times \{-1, +1\} \times \{1, \dots, N\}$ ,  $\mathcal{L} = \emptyset$
- Move (first part ...)

$$\underbrace{\begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet \rightarrow & \phantom{\bullet} \\ \hline \end{array}}_{x_t \in \Omega^{l-TASEP}} \rightarrow \underbrace{\begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \phantom{\bullet} & \bullet \\ \hline \end{array}}_{\text{'particle' displacement}} \rightarrow \dots \quad (6)$$

$$\underbrace{\begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet \rightarrow & \bullet \\ \hline \end{array}}_{x_t \in \Omega^{l-TASEP}} \rightarrow \underbrace{\begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet & \bullet \rightarrow \\ \hline \end{array}}_{\text{'lifting' move}} \rightarrow \dots \quad (7)$$

- Move (second part ...)

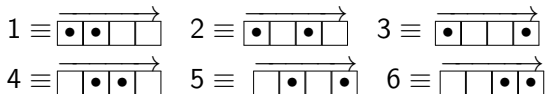
$$\dots \rightarrow \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \phantom{\bullet} & \bullet \\ \hline \end{array} \rightarrow \begin{cases} \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet \rightarrow & \phantom{\bullet} & \bullet \\ \hline \end{array} & p = \alpha \\ \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \phantom{\bullet} & \bullet \rightarrow \\ \hline \end{array} & p = \beta \end{cases} \quad (6b)$$

$$\dots \rightarrow \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet & \bullet \rightarrow \\ \hline \end{array} \rightarrow \begin{cases} \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet \rightarrow & \phantom{\bullet} \\ \hline \end{array} & p = \alpha \\ \begin{array}{|c|c|c|c|} \hline \phantom{\bullet} & \bullet & \bullet & \bullet \rightarrow \\ \hline \end{array} & p = \beta \end{cases} \quad (7b)$$

$x_{t+1} \in \Omega^{lTASEP}$

# TASEP (example)

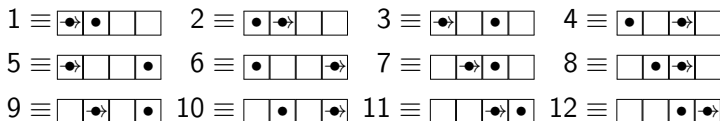
NB: Consider only the forward-moving sector (pbc):



$$P^{TASEP} = \frac{1}{2} \begin{bmatrix} 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & 1 & 1 & \cdot & \cdot \\ \cdot & \cdot & 1 & \cdot & 1 & \cdot \\ \cdot & \cdot & \cdot & 1 & 1 & \cdot \\ 1 & \cdot & \cdot & \cdot & \cdot & 1 \\ \cdot & 1 & \cdot & \cdot & \cdot & 1 \end{bmatrix} .$$

# Lifted TASEP (example)

NB: Consider only the forward-moving sector (pbc):



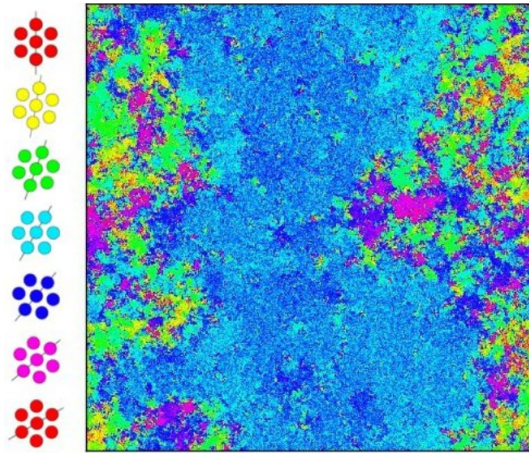
$$P = \begin{bmatrix} \boxed{\begin{matrix} \alpha & \beta \\ \cdot & \cdot \end{matrix}} & \boxed{\begin{matrix} \cdot & \cdot \\ \alpha & \beta \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \cdot & \cdot \\ \alpha & \beta \end{matrix}} & \boxed{\begin{matrix} \beta & \alpha \\ \cdot & \cdot \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \cdot & \cdot \\ \beta & \alpha \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \beta & \alpha \\ \cdot & \cdot \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \alpha & \beta \\ \cdot & \cdot \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \boxed{\begin{matrix} \alpha & \beta \\ \alpha & \beta \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \boxed{\begin{matrix} \cdot & \cdot \\ \beta & \alpha \end{matrix}} & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$

# Synopsis of mixing and relaxation times

| Algorithm    | mixing       | relaxation (inverse gap) |
|--------------|--------------|--------------------------|
| SSEP         | $N^3 \log N$ | $N^3$                    |
| TASEP        | $N^{5/2}$    | $N^{5/2}$                |
| Lifted TASEP | $N^2$        | $N^2$                    |

- continuous-space versions available (Kapfer & Krauth (2017))
- see Essler & Krauth (2023)

## Example IV: Equilibrium non-equilibrium



- Equilibrated sample of  $10^6$  disks (from Bernard & Krauth 2011, see also Li et al. 2022)

- A second revolution in Markov-chain Monte Carlo underway.
- Time scales of MCMC much better understood.
- Coupling: a way to perfect simulations.
- Non-reversible MCMC is what comes after the revolution.
- Lifting a practical method to create non-reversible algorithms.