

Entanglement between Demand and Supply in Markets with Bandwagon Goods

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Abstract

Whenever customers' choices (e.g. to buy or not a given good) depend on others choices (cases coined 'positive externalities' or 'bandwagon effect' in the economic literature), the demand may be multiply valued: for a same posted price, there is either a small number of buyers, or a large one – in which case one says that the customers *coordinate*. This leads to a dilemma for the seller: should he sell at a high price, targeting a small number of buyers, or at low price targeting a large number of buyers? In this paper we show that the interaction between demand and supply is even more complex than expected, leading to what we call the *curse of coordination*: the pricing strategy for the seller which aimed at maximizing his profit corresponds to posting a price which, not only assumes that the customers will coordinate, but also lies very near the critical price value at which such high demand no more exists. This is obtained by the detailed mathematical analysis of a particular model formally related to the Random Field Ising Model and to a model introduced in social sciences by T C Schelling in the 70's.

Keywords: Discrete choice, Social influence, Pricing, RFIM, Schelling.

1 Introduction

Interactions play a crucial role on the collective outcomes observed in social systems. The decision of leaving a neighborhood [34], to attend a seminar [35, 36] or a crowded bar [1, 2], to participate to collective actions such as strikes and riots [21], are particular examples where the emergent state may be at odds with widespread individual wishes. It has been further suggested that social interactions may explain the school dropout [13], the persistence in the educational level within some neighborhoods [15], the related consequences in the stratification of investment in human capital and economic segregation [7], the large dispersion in urban crime through cities with similar characteristics [18], the emergence of social norms [31], the labor market behavior and related unemployment patterns [41, 12], the housing demand [23], the existence of poverty traps [17], the smoking behavior [26, 25, 40], etc. In all these cases, social interactions give raise to multiple equilibria.

In economics there is a growing literature that recognizes the influence of social interactions in market situations like the subscription to a telephone network [3, 32, 42,

14] or the choice of a computer operating system [24], etc. The maximum price that each consumer accepts to pay for a given good (the *willingness to pay*), depends not only on his/her idiosyncratic preferences but also on the choice made by others [39, 33]. If the social interaction (called *externality* in economics) is positive, the willingness to pay for the most popular good increases. This leads to a so called *bandwagon effect* where this good is bought even by individuals who otherwise would have never made this choice. General aspects of bandwagon effects on the consumers demand have been discussed in the economics literature [27, 22, 6, 28, 33, 16, 10, 30]. The case when the willingness to pay for a good increases proportionally to the number of buyers, has received much attention. One shows that the demand curve (the relationship between the price and the quantity of goods that the customers are willing to buy) may be non monotonic. There is then a range of prices for which there are multiple market equilibria. The highest demand is Pareto-optimal, that is, at a given price, it satisfies the largest number of customers. Like a physical system trapped in a metastable state, the Pareto-optimal equilibrium may not be achieved. In economics, this is attributed to a lack of coordination among the customers – whereas when the high demand equilibrium is achieved, one says that the customers *coordinate*.

The case of binary choices (to buy or not to buy a single unit of an homogeneous good), with the social influence contributing additively to the willingness to pay, is formally related to the Random Field Ising Model (RFIM) at zero temperature[38] – the Ising spin corresponding to the binary choice of an agent, the exchange constant to the social coupling, and the quenched random field to the idiosyncratic part of the willingness to pay. Although we consider here a market context, this model has a wide range of applications in social (non economics) situations. Actually, this model is a variant of the “dying seminar”, one of the models introduced by the social scientist T. C. Schelling in the 70’s[35, 36], in order to explain how individual actions may combine to produce unanticipated social collective outcomes. We have extensively studied this model [30, 20] in the mean field case, as a function of the characteristics of the willingness to pay distribution. As expected, the existence, the number and the nature of multiple equilibria are generic properties: they only depend on the strength of the social coupling and on the number of maxima of the willingness to pay distribution, but not on its details. We have shown that some specific properties of the phase boundaries in parameter space are even universal: they are quantitatively, and not only qualitatively, identical for a wide family of different random field distributions. Interestingly, empirical analyses of some collective social behaviours have been shown to exhibit scaling laws predicted by the critical properties of this model [29, 8]. The model has also been extended to a dynamical setting with adaptive agents who update their beliefs, or equivalently their willingness to pay, according to the current market state [43, 37]. For a review of related approaches and issues, see [9].

Up to now, we only mentioned the customers behaviors facing a posted price. The analysis of the possible strategies of a seller (the offer or *supply*) has deserved much less attention. Within the economics literature, Granovetter and Soong [22] have discussed possible pricing strategies, i.e. what price to post in order to maximize the seller’s profit, within the same context of positive externalities. However, their analysis remains qualitative and notably does not explore in details the consequences of multiple

equilibria on pricing. A particular insightful paper is Becker’s note [5] attributing to social interactions the fact that popular restaurants do not increase their prices despite a persistent excess demand.

In this paper, we go one step further by considering a seller without competitors (monopoly market) facing the customer population described above. We analyze in its generality the seller’s profit optimization program. Thanks to the linear structure of the surplus (the difference between the willingness to pay and the actual price), we are able to characterize analytically the equilibria for any monomodal distribution of the customers’ willingness to pay. Here equilibrium means that offer equals demand (and this is also called a Nash equilibrium) – note that we consider a zero temperature setting.

Having an explicit mathematical model of both demand and supply allows us to uncover market characteristics that are specific consequences of the social interactions. The relevant parameters are the strength of the social interactions, the customers mean willingness to pay, and the strength of the ‘disorder’ (the standard deviation of the willingness to pay distribution). A convenient normalization allows us to discuss the results on phase diagrams in a two-parameters space. We determine the bounds of the regions corresponding to qualitatively different equilibria and we discuss the consequences of possible price settings in each region.

Obviously, the existence of multiple equilibria for the demand leads to the coexistence of multiple strategies for the seller. Within this domain, there is a first order transition: the optimal pricing strategy shifts from posting a high price attracting a small fraction of the population, to posting a much lower price to capture a greater share of the market. More surprisingly, this coexistence domain and transition line extend into the region where the demand is single valued.

As anticipated by Becker, when the optimal strategy is associated with a high demand (customers coordination), there is the risk that a low demand equilibrium exists for the same price. Our results show that this is the generic case, that is, there is a very large range of parameters for which posting the optimal price bears a risk, because getting the optimal profit requires that customers coordinate.

Another striking result is that the optimal price is generically just slightly below the price at which the high demand equilibrium disappears. A small change in the customers characteristics may lead to a decrease of this critical price. If this change is not anticipated by the seller, the posted price may become greater than the critical price, resulting in a collapse of the demand.

The paper is organized as follows. In section 2 we describe the generic properties of the model with positive-externalities and heterogeneous customers, in the case where the idiosyncratic willingness to pay has a smooth monomodal distribution. We assume that the monopolist is aware of the customer system properties, and is left with the problem of fixing the price. The profit optimization is discussed in section 3. In section 4 we summarize our results on a phase diagram, where regions corresponding to different economic situations are represented on a plane whose axis are the parameters of the customer system. The possible strategies for the monopolist are discussed in section 5. In section 6 we summarize the results.

2 Customers under social influence

2.1 The Demand

We consider a large number N of customers that must decide whether to buy or not a single unit of a homogeneous good at the price P posted by the (single) seller. We assume that the customers' *idiosyncratic willingness to pay* (IWP) is distributed among the population according to a probability density function (pdf) of mean H and standard deviation σ , with $0 < \sigma < \infty$. Upon buying at price P , agent i ($i = 1, \dots, N$) with IWP H_i gets a surplus \mathcal{S}_i linear in the fraction η of buyers in the population:

$$\mathcal{S}_i = H_i + J\eta - P, \quad (1)$$

where $J > 0$ is the strength of the social interactions. We assume rational buyers that maximize their surplus: agent i wants to buy if $\mathcal{S}_i \geq 0$, but not when $\mathcal{S}_i < 0$.

Quantities of interest are defined up to an arbitrary scale. It is convenient to make use of the following normalized parameters¹, hereafter denoted by low-case letters:

$$j \equiv \frac{J}{\sigma}, \quad h \equiv \frac{H}{\sigma}, \quad p \equiv \frac{P}{\sigma}, \quad \hat{p} \equiv \frac{P - H}{\sigma} = p - h, \quad (2)$$

With these definitions, i 's normalized IWP is $h_i \equiv H_i/\sigma = h + x_i$, where x_i is distributed according to a pdf $f(x)$ of zero mean and unitary variance. We are interested in the large N limit, in which case the fraction of buyers is given by the fixed point equation:

$$\eta = \int_{-s}^{\infty} f(x) dx = 1 - F(-s), \quad (3)$$

where F is the cumulative IWP probability distribution, and

$$s(j, \hat{p}; \eta) \equiv j\eta - \hat{p}. \quad (4)$$

Note that s depends² on p and h *only* through their difference \hat{p} . This remark is relevant for the next section, when dealing with the pricing problem.

For small j or high h , equation (3) has a unique solution: the inverse demand function³, that is the function $\hat{p}(\eta)$, exhibits a classical decreasing behavior (the larger the demand the smaller the price), like for systems without externalities. However, for low enough h , if j is larger than some critical value j_B , equation (3) may have multiple solutions. Thus, when social interactions are strong enough, $\hat{p}(\eta)$ has the characteristic “down-up-down” shape assumed by Becker [5] and others after him. These two regimes are illustrated on Fig. 1, Left.

¹In cases not studied here, $\sigma = 0$ (homogeneous IWP distribution), or $\sigma = \infty$ (fat tails), one would measure quantities in units of either J or H .

²In the argument of a function, we make use of “;” to separate quantities which have to be considered as parameters, here j and \hat{p} , from those which appear as variables, here η .

³In economics, the demand curve denotes the graph *price vs. quantity*, but it is meant to represent the demand function, the quantity as function of the price – hence the *inverse demand function* denotes the price as function of the quantity.

The above model is formally equivalent to the 'Dying seminar' model of T. C. Schelling [35, 36], reconsidered by M. Granovetter [21] for the formation of riots. In this model, every agent i decides to join or not (a regular seminar, a club, a riot...) if the number of participants $N\eta$ is larger than some idiosyncratic threshold, which is the analogous of $N(P - H_i)/J$. The model is also equivalent to a Random Field Ising Model (RFIM) [38] at zero temperature, with, obviously, $H_i - P$ playing the role of the quenched random field and J the one of the coupling strength. However, the questions of interest here do not all have an interpretation in the physics context of the RFIM. This is notably the case for the issues addressed in the present paper whose focus is on the pricing strategy of a seller.

2.2 Main steps for the analysis of the demand

For completeness and later use in the analysis of the pricing problem, the main ingredients for the analysis of the demand are presented here. We give the main results when the willingness to pay has a smooth monomodal pdf $f(x)$ whose support is the full real axis ($f'(x) = 0$ only at the maximum and in the asymptotic limits $x \rightarrow \pm\infty$). The full detailed analysis, including generalizations to other types of pdf, in particular to multimodal ones and distributions with fat tails, may be found in [20].

All the numerical illustrations in this paper correspond to a logistic distribution of cumulative function $F(x) = (1 + e^{-\beta x})^{-1}$, where we set $\beta = \pi/\sqrt{3}$ in order to have a unitary variance. Notice however that for the general results presented hereafter we need neither assume f to be symmetric nor that its maximum is at $x = 0$.

Since equation (3) may have several solutions, it is convenient to consider the inverted equation, introducing the function Γ :

$$\eta = 1 - F(-s) \iff s = \Gamma(\eta). \quad (5)$$

The properties of the IWP distribution which matters are those of the function Γ . This function Γ is always a single valued function: it increases monotonically⁴ when η goes from 0 to 1. For a monomodal distribution, Γ has a single inflexion point.

Replacing s in the r.h.s. of (5) by its expression (4) yields

$$\hat{p} = \mathcal{D}(j; \eta) \quad (6)$$

where

$$\mathcal{D}(j; \eta) \equiv j\eta - \Gamma(\eta), \quad (7)$$

depends on j but not on \hat{p} . These functions Γ and \mathcal{D} play a central role in the analysis of the demand.

Given the parameters j , \hat{p} and the pdf $f(x)$ characterizing the customers' system, \mathcal{D} determines the *inverse demand function*

$$p^d(\eta) = h + \mathcal{D}(j; \eta), \quad (8)$$

which depends on both parameters h and j .

⁴Here from $-\infty$ to $+\infty$. In the case where the IWP is defined on an interval so that the normalized variable x lies in $[x_m, x_M]$, Γ takes the finite values $\Gamma(\eta = 0) = -x_M$ and $\Gamma(\eta = 1) = -x_m$.

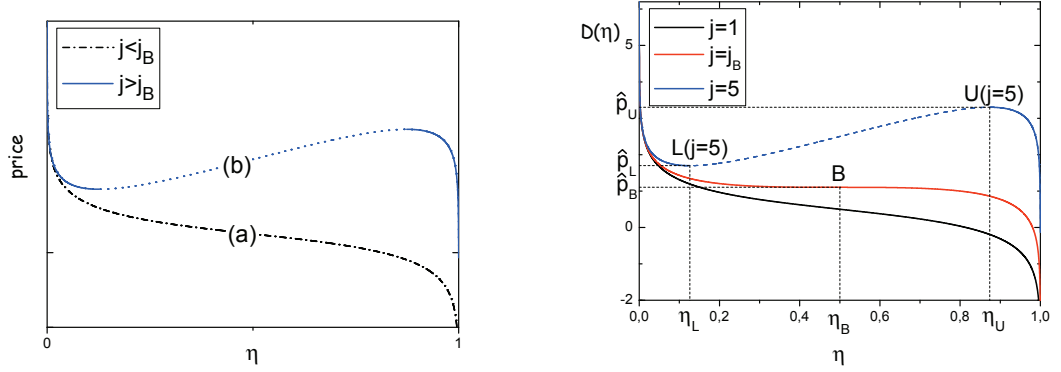


Figure 1: *Left: Demand curve (price vs. fraction of buyers) for different values of j in the case of a logistic distribution of the IWP: (a) classical behaviour at low social influence or high mean willingness to pay; (b) multiply valued function at large social influence $j > j_B$ and low enough mean willingness to pay (dashed: unstable equilibria). Right: The associated function \mathcal{D} for $j = 1 < j_B$ (classical behaviour at low social influence or high mean willingness to pay), $j = j_B \approx 2.21$ and $j = 5 > j_B$ (multiply valued function at large social influence; dashed: unstable equilibria).*

The demand equilibria $\eta^d(\hat{p}, j)$ are the solutions to (6). Graphically, at a given value of j , they correspond to the intersection(s) of the function $y = \mathcal{D}(j; \eta)$ with the horizontal line $y = \hat{p}$. Plots of $\mathcal{D}(j; \eta)$ against η for different values of j are presented on Figure 1, Right. According to Equ. (8), these curves, shifted vertically by the value h (the average IWP of the population) give the demand curves like those represented on Fig. 1, Left.

The stable equilibria of the demand satisfy

$$\mathcal{D}'(j; \eta) = j - \Gamma'(\eta) \leq 0 \quad (9)$$

where the prime, $'$, denotes the derivative with respect to η at j fixed. Equilibria with $\mathcal{D}' > 0$ are unstable and are usually excluded in economic discussions.

From the stability condition (9), and noting that Γ' has a unique absolute minimum $\Gamma'(\eta_B) = \min_{\eta} \Gamma'(\eta) = \frac{1}{f_B} > 0$, where $f_B \equiv \max_x f(x)$, one gets that there is a critical value j_B of the social strength, defined by $j_B \equiv 1/f_B$: whenever $j \leq j_B$ there is a unique solution $\eta^d(\hat{p}, j)$ to (6), whereas for $j > j_B$ there is a range of \hat{p} values with multiple solutions. Indeed, for $j > j_B$, \mathcal{D} has two relative extrema⁵, a minimum at $\eta_L(j)$ and a maximum at $\eta_U(j)$, with $\eta_L(j) \leq \eta_B \leq \eta_U(j)$. These limiting values are given by the marginal stability condition

$$\mathcal{D}'(j; \eta) = 0 \quad (10)$$

⁵For multimodal pdfs, the maximum number of such extrema is 1 plus the number of modes of the pdf [20]. Note that in the context of the RFIM, most studies consider the monomodal, Gaussian, case, or the bimodal case with $H_i = \pm H$.

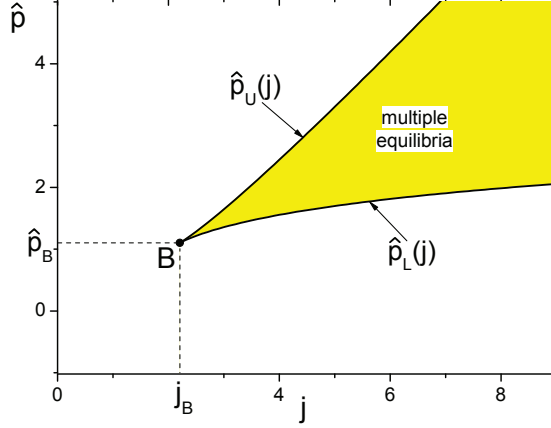


Figure 2: *In the plane $(j, \hat{p} = p - h)$, customers' phase diagram for a smooth monomodal IWP distribution, illustrated with the case of the logistic distribution.*

leading to $\Gamma'(\eta_U) = \Gamma'(\eta_L) = j$, and the corresponding \hat{p} values, $\hat{p}_\Lambda(j) \equiv \mathcal{D}(j; \eta_\Lambda(j))$, $\Lambda = L, U$. One has $\hat{p}_B \leq \hat{p}_L \leq \hat{p}_U$.

The definition (7) of \mathcal{D} and the condition (10) imply that the phase boundaries are given by the Legendre transform of the function Γ defined in (5). This fact allows to get various generic properties of the phase diagram, resulting from convexity properties that are associated to the Legendre transform (see [20] for details). These properties have not been studied before in the context of the RFIM, where the focus is rather on the nature of the transitions, with universal properties which are known, or assumed to be, independent of the distribution of the random field.

2.3 Customers' phase diagram

We summarize the properties of the demand on a phase diagram of abscissas j and ordinates \hat{p} , where we represent the boundaries between phases of qualitatively different behaviors. Whenever \hat{p} and/or j change across one of these boundaries, a stable demand equilibrium appears or disappears abruptly. Thus, these boundaries are lines of non-analyticity.

Figure 2 presents the phase diagram corresponding to the unitary variance logistic distribution. The multiple solutions region (shadowed on the figure) appears at the bifurcation point $B \equiv (j_B, \hat{p}_B)$. The boundaries are given by the curves $p = \hat{p}_L(j)$ and $p = \hat{p}_U(j)$ where \hat{p}_L is concave and \hat{p}_U is convex. At the bifurcation point B the two branches meet forming a cusp, and beyond j_B the width of the multiple solutions region increases monotonically with j , as illustrated in the figure.

Whenever $\hat{p}_L(j) < \hat{p} < \hat{p}_U(j)$, there are thus multiple possible demands given by the two stable solutions, that we denote $\eta_L^d(j, \hat{p})$ on the low- η manifold, with $0 < \eta_L^d(j, \hat{p}) < \eta_L(j)$, and $\eta_U^d(j, \hat{p})$ on the large- η manifold, with $\eta_U(j) < \eta_U^d(j, \hat{p}) < 1$. There is a

gap in the possible (stable) equilibrium values of η : the interval $[\eta_L, \eta_U]$ corresponds to unstable equilibria. The demand equilibrium in the large- η manifold, η_U^d , is Pareto optimal: not only it gives positive surpluses to more individuals, but these surpluses are systematically larger than those corresponding to the lower demand equilibrium η_L^d , because the surplus function (1) increases with η . The high demand (Pareto optimal) equilibrium, $\eta = \eta_U^d$, requires customers coordination: it is the demand sustained by the social interactions. If coordination fails, the system stabilizes in the low demand equilibrium, $\eta = \eta_L^d$, on which everybody has a smaller surplus. As we will see in the next Section, the possibility of coordination failures has dramatic consequences on the pricing strategies.

3 The Supply: Monopoly Market

In this section we examine the consequences of customers social interactions on the pricing strategy of a monopolist who has to determine the price P and how many units $N\eta$ of the good to put in the market in order to maximize his profit.

3.1 Underlying market structure

A standard economics viewpoint is that there exists, on one side, a Demand curve, relating the price to the quantity that consumers are willing to buy at that given price; and on the other side, a Supply curve, giving the price that the seller will post in function of the quantity asked by the consumers. The Demand curve (resp. the Supply curve) is assumed to be monotonously decreasing (resp. increasing) with increasing quantity, and the market (or equilibrium) price is given by the intersection of the two curves. As recalled in the previous section, in the present case of market with externalities there is a wide range of parameters for which the Demand curve is non monotonous, and only the parts with negative slope can correspond to stable equilibria: for $j > j_B$ the domain of accessible η -values is disconnected. On the Supply side, in the present model there is no Supply curve *per se*: it is here assumed that the seller can produce any quantity of goods, and he/she will produce the quantity corresponding to the price that maximizes his/her profit. As shown in the Appendix, Section A.1.1, this optimization program has an interesting underlying mathematical structure for several reasons. First, it leads to an effective Supply curve: the maximization of the profit can be written as the solution of an equality between the demand (as computed in the previous section) and an effective supply function. This allows for a discussion within an (almost) classical economics setting (in Physics one would say that this gives a physical interpretation of the underlying market structure). Second, there is an unexpected formal analogy between the demand problem and the profit maximization problem. This allows us to simplify the analysis of the supply problem. To our knowledge, these properties have not been noted before in the economics literature. Finally, despite the simplification brought by the analogy, the pricing issue remains more involved than the analysis of the demand, since for $j > j_B$ there is a range of prices for which the demand is multi-valued, and the domain in η where the profit has to be maximized is non-connected.

We first briefly present the mathematical analysis of the profit maximization problem that has to be solved by the seller, as evoked above. We then discuss the optimal pricing strategies as a function of j and h , the parameters characterizing the customers population. Most mathematical details are left to the Appendix.

3.2 Supply function

3.2.1 The optimization problem

If C is the production cost per unit, the seller's profit is $\Pi = (P - C) N\eta$. For simplicity we assume that C is independent of the total number of produced units. One can easily find many examples of constant marginal cost, and in some cases quasi-null marginal cost, like the cost of replicating software, musical or audiovisual digital files⁶.

The relevant normalized variables corresponding to the supply are $\frac{H-C}{\sigma}$ and $\frac{P-C}{\sigma}$. Since the demand only depends on the difference $\hat{p} = p - h = \frac{P-H}{\sigma}$, which is invariant under the shift of C/σ on both p and h , we can use the results of the demand analysis without any change. Thus, hereafter we interpret h and p as excess values with respect to the normalized cost C/σ . With this convention, the monopolist has to choose the price p in order to maximize his normalized (in the same sense as equation (2)) profit

$$\pi(\eta, p) \equiv \frac{\Pi}{N\sigma} = p\eta, \quad (11)$$

under the assumption that η and p are related through the demand equilibrium equation (8). The maximum of the profit may correspond to a low demand with a high price or to a high demand and a small price, depending on the customers characteristics (mean willingness to pay and strength of the social interactions) in a non trivial way, as may be seen on Figure 3.

The optimal price is given by the solution(s) of $\partial\pi/\partial p = 0$ that satisfy the maximum (second order) condition $\partial^2\pi/\partial p^2 < 0$, and by inspection of the profit at the boundaries of the accessible η domain.

3.2.2 Analogy with the demand analysis

The maximization problem can be cast into the same mathematical framework as the analysis of the demand. That is, the extremum condition $\partial\pi/\partial p = 0$ can be written as the following condition on the quantity η that has to be supplied by the monopolist,

$$-h = \tilde{\mathcal{D}}(j; \eta) \quad (12)$$

and the second order condition $\partial^2\pi/\partial p^2 < 0$ can be written as

$$\tilde{\mathcal{D}}'(j; \eta) \leq 0, \quad (13)$$

⁶One can note that a standard decreasing marginal cost would lead, in the large N limit, to a total cost that can be neglected (compared to $N\eta$). Taking into account a total cost that depends on $N\eta$ would require an analysis of finite size effects, which is out of the scope of the present paper.

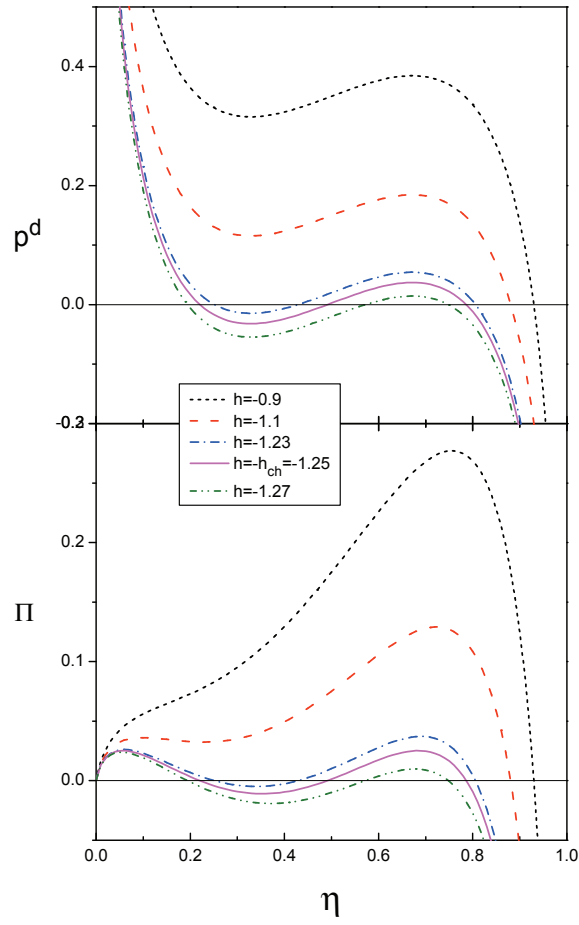


Figure 3: Price (upper figure) and profit (lower figure) for different values of h , and $j = 2.5$. The maximal profit changes from a high price-low supply strategy (for $h < h_{ch}$) to a low price-high supply strategy (for $h > h_{ch}$)

where $\tilde{\mathcal{D}}(j; \eta) \equiv \frac{d}{d\eta}[\eta \mathcal{D}(j; \eta)]$ can be written as

$$\tilde{\mathcal{D}}(j; \eta) = 2j\eta - \tilde{\Gamma}(\eta) \quad (14)$$

with the function $\tilde{\Gamma}$ is defined by

$$\tilde{\Gamma}(\eta) \equiv \frac{d}{d\eta}[\eta \Gamma(\eta)]. \quad (15)$$

Comparing (14) with the definition of the demand function \mathcal{D} , Equ. (7), and (12) and (13) with the equations for the Demand, (6) and (9) respectively, one sees that the equations have the very same structure as the ones for the demand, with $-h$, $\tilde{\Gamma}$, $\tilde{\mathcal{D}}$ and $2j$ playing the roles of, respectively, $\hat{p} = p - h$, Γ , \mathcal{D} and j . In order to take full advantage of this analogy, we need to assume hereafter that, like $\Gamma(\eta)$, $\tilde{\Gamma}(\eta)$ is monotonically increasing from $-\infty$ to $+\infty$ when η goes from 0 to 1, and that it has a single inflexion point. As detailed in the Appendix, Section A.1.2, this is true under a not a very stringent condition on the IWP distribution.

Equation (12) and (13) characterize the *relative* maxima of the profit in interior regions of the accessible η -domain. However, as already said, for $j > j_B$ and $\hat{p}_L(j) < \hat{p} < \hat{p}_U(j)$, values of η in the range $[\eta_L(j), \eta_U(j)]$ should not be considered as they correspond to unstable equilibria. As a consequence, there may exist maxima at the boundaries of the forbidden interval. In Section 4.2.1 we show that when they exist, these are always sub-optimal maxima so that we may first ignore them in the following. Nevertheless, as we will see in Section 5, they play an important role in the discussion of the possible monopolist's strategies.

3.2.3 An effective supply function

With these clarifications, the analysis follows the same lines as that of the demand. Given the parameters h and j characteristic of the customers population, the solution(s) of $-h = \tilde{\mathcal{D}}(j; \eta)$ determine $\eta^s \equiv \eta(j, h)$ which gives the number of goods $N\eta^s$ to be supplied by the monopolist. Introduction of η^s into (8) allows to determine the price $p^s = p^d(\eta^s)$ to be posted which, interestingly, is given by the difference between the function \mathcal{D} of the demand and the function $\tilde{\mathcal{D}}$ of the supply optimization:

$$p^s(j, h) = \mathcal{D}(j; \eta^s) - \tilde{\mathcal{D}}(j; \eta^s). \quad (16)$$

Alternatively, the solution of seller's problem can be expressed as finding the solution(s) η^s of the equality between demand and supply:

$$p^d(\eta) = p^s(\eta) \quad (17)$$

where $p^s(\eta)$ is an effective supply function, defined by

$$p^s(\eta) \equiv -\eta \mathcal{D}'(j; \eta) = \eta[\Gamma'(\eta) - j] \quad (18)$$

(see the Appendix A.1.1 for details).

The corresponding profit is obtained through introduction of η^s and p^s into (11). If several solutions exist, the monopolist should select the one corresponding to the maximum maximorum of the profit.

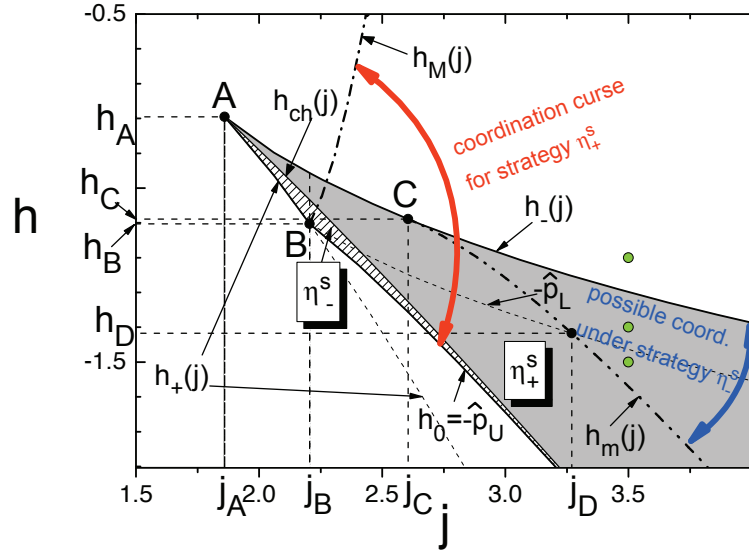


Figure 4: Supply phase diagram with indication of the region (large heavy double-arrow line) where the η_+^s strategy may fail due to lack of customers coordination. The small (rightmost) heavy double-arrow line indicates the region where a seller targeting the η_-^s equilibrium might benefit from a coordination success. The three green dots correspond to values used on Figure 9. Values for the logistic: $j_A = 27\sqrt{3}/(8\pi) \approx 1.86$, $h_A \approx -0.80$, $j_B \approx 2.21$, $h_B \approx -1.10$, $j_C \approx 2.61$, $h_C \approx -1.09$, $j_D \approx 3.27$, $h_D \approx -1.42$

4 The Monopoly Phase Diagram

In this section we discuss the optimal pricing strategies as a function of the parameters characterizing the customers population. Like for the demand, we represent the regions with similar properties on a phase diagram (of axis j and h in this case). Whenever h and/or j change across the boundaries of such regions either the optimal price jumps discontinuously or the number of pricing strategies (extrema of π) changes. Taking advantage of the formal analogy pointed out in the previous section, the construction of the phase diagram follows the same lines as for the demand. However, the supply problem is more involved because for $j > j_B$ one must also take into account the fact that the customers' system has two possible Nash equilibria, and that the range of values $\eta \in [\eta_L(j), \eta_U(j)]$ are unstable equilibria of the demand. Figure 4 shows a complete phase diagram for the particular case of a logistic distribution. Its main features, that we discuss thoroughly in the following sections, are generic for any smooth distribution of the IWP having a single maximum and satisfying condition (A-13). Details of the construction are given in the Appendix, Section A.3.

4.1 Seller's Dilemma

In this section we discuss the domain of existence of multiple strategies, in which the seller faces the following dilemma: should he sell at low price to a large number of customers, or at high price to a small number of customers?

4.1.1 A first order transition

Like for the demand, there is a bifurcation in the behavior of the optimal price, that here takes place at a critical value of j defined by

$$j_A = \tilde{\Gamma}'(\eta_A)/2, \quad \text{with} \quad \eta_A \equiv \arg \min_{\eta} \tilde{\Gamma}'(\eta). \quad (19)$$

with $\tilde{\Gamma}$ defined in (15). This gives in the plane (j, h) a critical point $A = (j_A, h_A)$, analogous for the supply to the point B in the demand phase diagram. One can show that $\eta_A \leq \eta_B$ and $j_A \leq j_B$.

When $j > j_A$ the extremum condition for the profit, equation (12), presents multiple solutions for some range of values of h . In the (j, h) plane, the boundaries of the domain of multiple solutions are given by the Legendre transform of the function $\tilde{\Gamma}$. More precisely, they are given by the curves $h_{\pm}(j) = -\tilde{\mathcal{D}}(j; \eta_{\pm}(j))$ where $\eta_{-}(j) < \eta_A$ and $\eta_{+}(j) > \eta_A$ are, respectively, the minimum and the maximum of $\tilde{\mathcal{D}}(j; \eta)$, both satisfying the marginal stability condition $\tilde{\mathcal{D}}'(j, \eta_{\pm}) = 0$ (for an illustration, see the left-hand side panels of Figure 9, in section A.2). Note that this curves $h_{\pm}(j)$ are the analogous, for the monopolist problem, of the curves $\hat{p}_{U,L}(j)$ giving the boundaries of the multiple solution domain for the demand, as discussed Section 2.

If (j, h) lies outside the multiple solutions region, the profit has a single maximum as η goes from 0 to 1. Thus, the profit optimization has a unique solution, and the optimal supply η^s , the price to be posted p^s and the expected profit are obtained using equations (12), (8) and (11) respectively.

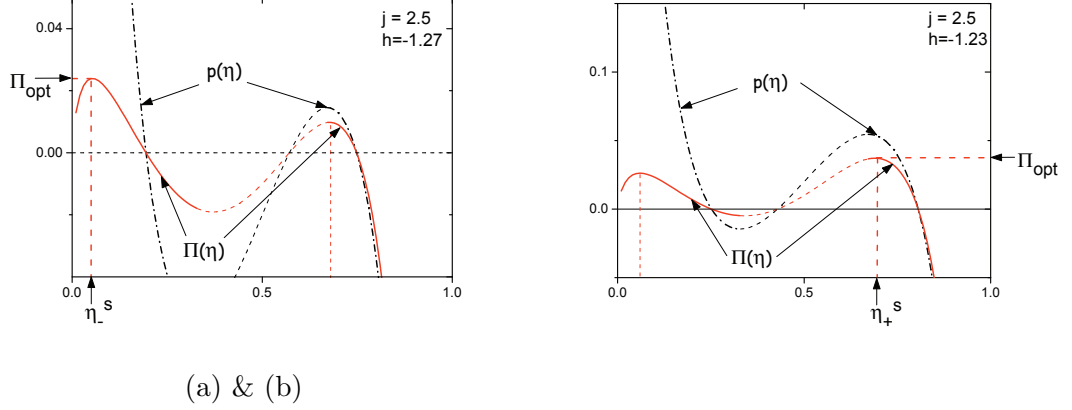


Figure 5: Price and profit as a function of the supply η for $j = 2.5$ (for which $h_{ch} \approx -1.247$), for two values of h . The supplies η_-^s and η_+^s and the profits of the optimal strategies are indicated. (a) $h = -1.27 < h_{ch}$: the optimal strategy lies on the low- η branch ; (b) $h = -1.23 > h_{ch}$: the optimal strategy lies on the high- η branch, at a value of η very close to the point where the high- η branch disappears.

Within the domain of multiple solutions (hence $j > j_A$ and $h_+(j) < h < h_-(j)$), the two local maxima of the profit correspond to two different strategies for the monopolist: either to attract a large fraction of buyers at low prices (solution $\eta_+^s(j, h)$) or to target few buyers willing to pay high prices (solution $\eta_-^s(j, h)$). There is a first order transition at a critical value $h_{ch}(j)$ within the coexistence region, where the optimal strategy (corresponding to the maximum maximorum of the profit) switches abruptly from one branch to the other. On this line $(j, h_{ch}(j))$, both strategies give the same profit (and this is what defines $h_{ch}(j)$), but the corresponding prices are very different. Figure 5 illustrates the transition between the low-demand and the high-demand optimal strategies when h changes across the value $h_{ch}(j)$ for $j = 2.5$. Another example of this strategy-switching has been presented in [19] for a particular IWP distribution.

At fixed $j > j_A$, if h is small enough to be outside the coexistence region, the optimal price is unique. If h increases, this maximum of the profit can be followed into the coexistence region, where it corresponds to values $\eta_-^s(j, h)$ on the low- η branch of $\tilde{\mathcal{D}}$, up to $h = h_-(j)$ where it disappears. Conversely, decreasing h from a value high enough to have a unique demand, the solution $\eta_+^s(j, h)$ lying on the large- η branch of $\tilde{\mathcal{D}}$ is met upon entering the coexistence region and can be followed down to $h = h_+(j)$ where it disappears.

4.1.2 Beyond the simple first order picture

Besides the point A , there is an additional singular point, $B = \{j_B, h_B = -\hat{p}_B\}$, a mirror of the customers' point B , lying on the boundary line $h = h_+(j)$. For $j > j_B$, the domain of existence of the high-supply strategy η_+^s has a lower bound of viability given by the condition that the optimal price for the high- η strategy has to be positive.

There is a line where the optimal price for the high- η strategy is zero —that is, given our convention, the actual optimal price is equal to the production cost. This null-price curve is given by $h_0(j) \equiv -\hat{p}_U(j)$, where $\hat{p}_U(j)$ is the boundary of the customers U solution (see equation (10)). As may be seen on Figure 4 the line $h_0(j)$ starts at point B on the line $h_+(j)$ and verifies $h_0(j) > h_+(j)$ for all $j > j_B$.

Interestingly, for j in the range $j_A < j < j_B$, the monopolist has two possible strategies, hence in a domain where the demand is single valued. In this domain, since the fraction of buyers is a unique function of the price, the seller can drive the customers to the optimal profit equilibrium by just posting the corresponding price.

In contrast, for $j > j_B$ ($\geq j_A$), as seen in Section 2.1 the customers system has multiple equilibria: a low- η risk-dominant one and a high- η Pareto-optimal equilibrium which needs coordination of the buyers. The actual equilibrium reached by the customers system may not be the one targeted by the monopolist at the posted price, due to coordination failure. This problem has been mentioned by Becker in his note on restaurant pricing strategies [5]. In the next section we determine precisely the parameter region in the phase diagram where choosing a pricing strategy can be subject to such epistemic uncertainty.

4.2 Pricing when the demand is multi-valued

In this section we are interested in the possible outcomes when the values of h and $j > j_B$ are such that the optimal price for the seller may correspond to a situation where the demand is multi-valued. Then, when posting a low price in order to meet the optimal large demand, the seller runs the risk of finding himself with a low demand if coordination of the customers fails.

Consider the demand $\eta = \eta^d$ as function of the price p . As discussed section 2, in the range of interest here, there is two branches, a low η ($0 \leq \eta \leq \eta_L$) and a high- η ($\eta_L < \eta_U \leq \eta \leq 1$), with a range of (shifted) prices $[\hat{p}_L(j), \hat{p}_U(j)]$ where the two branches overlap. We can look at the profit as one increases the price, following separately each branch. The profit may have (relative) maxima at some of the boundaries ($\eta = 0, \eta_L, \eta_U, 1$), and/or in the interior parts, the latter giving the solutions η_-^s on the low- η branch and η_+^s on the large η branch (see Section A.3.5 for more details).

Hence, whenever the monopoly chooses the low-supply strategy η_-^s , it expects that the customers system selects the low- η^d solution. Conversely, if the monopoly chooses the high-demand strategy η_+^s , it expects the customers system to select the large- η^d solution. Thus, we can first analyze each branch separately. Numerical illustrations of the different situations are given in the Appendix, Section A.2.

4.2.1 Pricing without need of coordination - Low-demand manifold

Consider first the (relative) maximum(s) of the profit at low values of η , i.e. in the domain $\eta \in [0, \eta_L]$. These solutions correspond to fractions of buyers on the low- η^d branch of the demand (see figure 1, Right) where the customers' equilibrium does not need coordination. We have seen that it corresponds to the optimal strategy below the first order transition, that is whenever $h < h_{ch}(j)$ (see Figure 6 for the details).

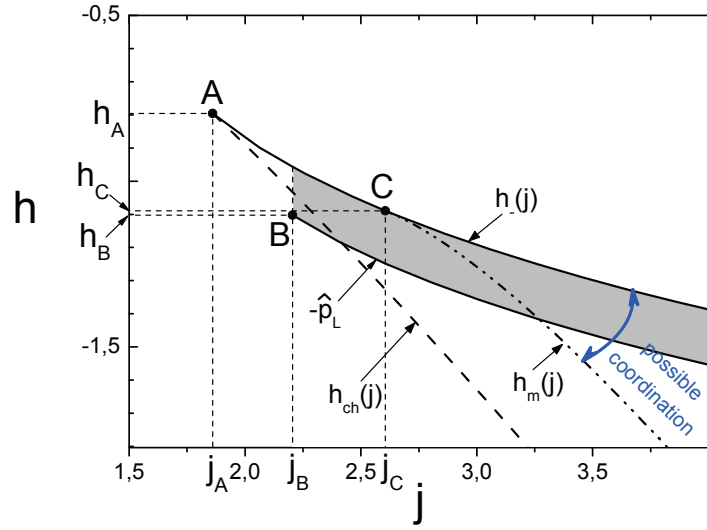


Figure 6: *Supply phase diagram: properties of the low- η^s extrema, that exist for any $h < h_-(j)$ and $j > j_A$ (for $j < j_A$ there is a single optimal supply). The low- η^s solution corresponds to the absolute maximum of the profit whenever $h < h_{ch}(j)$. For $j > j_B$ and for values of h inside the grey region ($-\hat{p}_L(j) < h < h_-(j)$) there is, besides the maximum at η_-^s , a maximum of π at η_L for a price $p = \hat{p}_L(j) + h$. In the region $h_m(j) < h < h_-(j)$ a (not optimal) strategy targeting η_-^s may give raise to coordination among customers. In that case, the fraction of buyers, hence the profit, is larger than expected.*

On the low- η^s branch ($h < h_-$) the profit has one maximum at η_-^s , and, for $-\hat{p}_L < h < h_-$, a second maximum at the boundary η_L , which is always suboptimal (see the Appendix, section A.5.4).

The solution η_-^s may lie in the region where the customers' system has multiple equilibria. We find (Appendix, Section A.4) that this happens above the line $h_m(j)$, a region inside the coexistence domain (Figure 4, heavy double-arrow line) where this solution η_-^s exists but is not the best one.

Suppose that, starting from a value of h below $h_{ch}(j)$, h increases. Assuming smooth ("adiabatic") changes in the population parameters and behavior, the posted price has to change smoothly, following the demand on the low η branch. Up to $h = h_m(j)$, the posted price remains in the region for which \hat{p} gives a unique solution for the demand. Beyond $h_m(j)$, that is for $h_m < h < h_-$ and j larger than some value j_C (see Section A.4), the low- η^s relative maximum is such that $\hat{p}_L < \hat{p} < \hat{p}_U$, i.e. it lies in a region where the customer system has multiple equilibria. Once in this regime, if for any reason the customers do coordinate, the demand and hence the resulting profit are much higher than the one expected without coordination. Note that the profit at this price, for the high demand, is not the best profit that the seller can make with the demand on the high demand branch (see below).

One should note that no hint of the existence of an alternative strategy can be obtained from smooth changes in the price. Thus, if the seller lacks exact information on the population characteristics, he will remain unaware of the existence of the high- η^s strategy. Conversely, even if the seller knew that a high- η^s solution exists, choosing the (suboptimal) local maximum on the low- η branch represents a possible risk adverse strategy, allowing to avoid losses due to coordination failures.

4.2.2 Pricing expecting coordination - The curse of coordination

Let us now analyze the outcomes when the monopolist chooses to target the large fraction of customers, $\eta = \eta_+^s$. As we have seen, for $j > j_B$ such solutions exist only for an average willingness to pay large enough ($h > h_0(j)$, see section 4.1 and figures 9), with fractions of buyers η_+^s on the high- η branch of $\tilde{\mathcal{D}}(j; \eta)$. They satisfy $\eta_U < \eta_+ \leq \eta_+^s \leq 1$. We know that this strategy gives the largest profit above the first order transition line, that is for $h > h_{ch}(j)$.

Let us determine the range of h values for which this strategy corresponds to a price that falls within the domain where the demand is multi-valued. That is, we consider the possibility that the optimal price p^s is such that $\hat{p} = p^s - h$ lies in the range $[\hat{p}_L(j), \hat{p}_U(j)]$, for which there are two possible demands, the one expected by the seller, and the one on the low η^d branch. This is the case if η_+^s lies in the range $[\eta_U, \eta_M(j)]$, where $\eta_M(j)$ is the value on the high demand branch for $\hat{p} = \hat{p}_L(j)$. According to (6), η_M is given by $\mathcal{D}(j; \eta_M) = \hat{p}_L(j)$. The limiting case where the seller's price p^s corresponds to this demand η_M is obtained when h takes the value h_M which satisfies the maximum condition (12) for $\eta = \eta_M$, that is

$$h_M(j) \equiv -\tilde{\mathcal{D}}(j; \eta_M) \quad (20)$$

The other limiting case corresponds to $\hat{p} = p^s - h = \hat{p}_L(j)$, which occurs if $h = -\hat{p}_U(j)$.

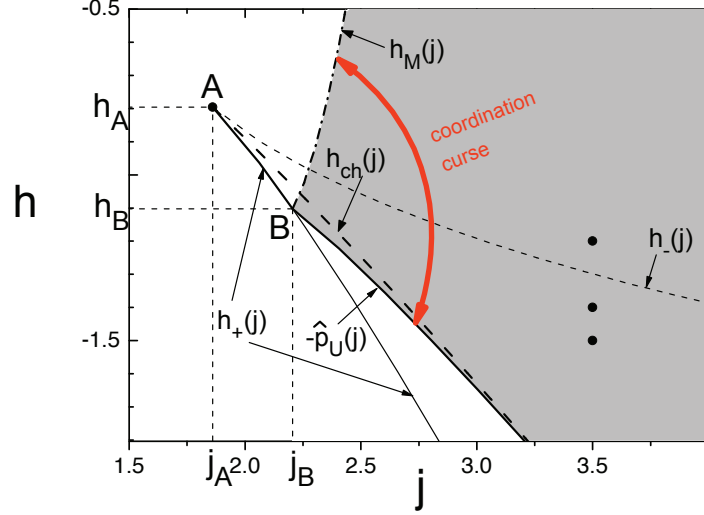


Figure 7: *Supply phase diagram: properties of the high- η^s extrema that exist for any $h > h_+(j)$ if $j_A < j < j_B$, and for $h > -\hat{p}_U(j)$ if $j > j_B$ (for $j < j_A$ there is a single optimal supply). The high- η^s strategy targets a fraction of buyers $\eta_+^s > \eta_+$. This solution corresponds to the absolute maximum of the profit whenever $h > h_{ch}(j)$. For $j > j_B$ and for values of h inside the grey region ($-\hat{p}_U < h < h_M$), this strategy is optimal provided customers coordinate. If coordination is not achieved, the actual customers' equilibrium lies on the low- η^d branch, providing a profit smaller than expected. The three black dots correspond to values used on Figure 9.*

Thus, for the mean willingness to pay in the range $[-\hat{p}_U(j), h_M(j)]$, the strategy η_+^s drives the customers into the region of multiple solutions for the demand, making uncertain the actual outcome. In the plane (j, h) , the line $h_M(j)$ starts at the point B (since $-h_M(j_B) = \tilde{\mathcal{D}}(j_B; \eta_B) = \hat{p}_U(j_B)$), and increases with j faster than the line $h = -\hat{p}_L(j)$ because for positive prices $\mathcal{D}'(j; \eta) < 0$ so that (20) gives $h_M(j) > -\hat{p}_L(j)$. Thus, posting a price corresponding to η_+^s in the region where this strategy is optimal, i.e. for $h_{ch}(j) < h < h_M(j)$, may have an uncertain outcome because this price leads to the optimal profit only if the actual fraction of customers lies on the high- η^d manifold. If the customers fail to coordinate, the fraction of buyers will correspond to the solution lying on the low- η^d manifold at this same price, giving a profit much smaller than the expected one. The uncertainty region of the high- η^s supply strategy for the case of the logistic distribution, represented by a large heavy double-arrow line on figures 4 and 7, is seen to cover a wide range of parameters, much larger than the region where multiple (locally optimal) strategies exist for the monopolist.

In addition, another striking result is that the optimal strategy corresponds to a price value very close to the boundary where the demand sustained by the social influence, that is the high- η branch, disappears (η^s slightly larger than η_U , \hat{p}^s just

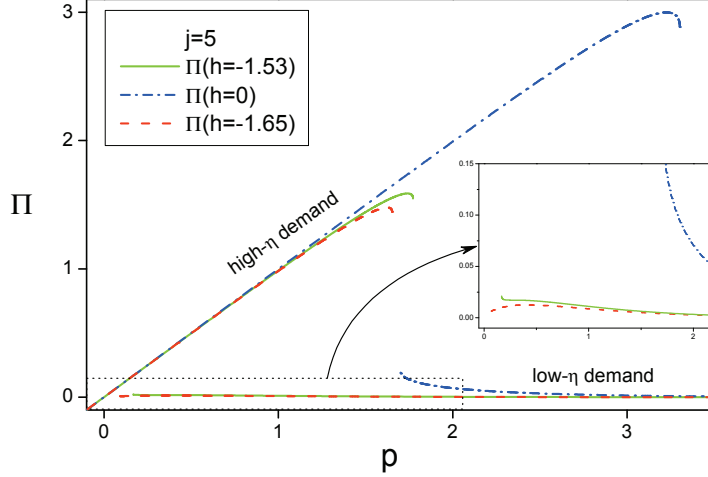


Figure 8: *Profit vs. price for $j = 5$ and three different values of h . The optimal profit is obtained for the demand sustained by the social interactions (high η branch), at a price slightly below the critical price at which the high demand disappears.*

below \hat{p}_U). This is illustrated on Figure 8 which shows the profit as a function of the price, at a large value of j and for different values of h – see also Figure 5 above and Figure 9, Section A.2. Hence a small change in the population characteristics, if unexpected by the seller, may drive the current posted price outside the domain of existence of the high profit solution.

5 Discussion: pricing under epistemic uncertainty

In his note on pricing of goods with bandwagon properties, like restaurants, bestseller books, successful plays in theaters, etc, Becker [5] provides an explanation of apparently irrational pricing, that he attributes to the fact that the preferences for such goods are highly dependent on social influences. His qualitative analysis assumes implicitly that the optimal strategy for the seller corresponds to the large supply branch. He argues that the price of these goods does not increase despite a chronic excess demand for fear of what he calls “fickleness” of the consumers, that is nothing but the fragility of coordination. As we develop in this section, our mathematical modeling shows that there may be at least another explanation to the pricing behavior.

5.1 Possible strategies to overcome coordination failures

Consider the parameter regime where the optimal strategy corresponds to the large- η^s solution, in the region where it requires coordination — that is, $h_{ch} < h < h_M$ and $j > j_B$. If the population fails to coordinate, the actual fraction of buyers at equilibrium

will lie on the low-demand curve. May the monopolist drive it to the optimal profit solution, on the high- η branch?

A reasonable assumption is that for a small change in any parameter, the demand will respond smoothly, whenever possible. Hence, if the system is in state η^d on one branch of the multiple equilibrium region of the demand, away from the end points η_L and η_U , a small change in price, i.e. in \hat{p} , will slightly shift the demand along the same branch.

Anticipating the risk of coordination failure, the seller may then first post a price low enough to reach the large- η^d customers' equilibrium outside the multiple-solutions region (see figures 9 for graphical illustrations and Section A.2 for further discussions), and then smoothly increase the price to reach its optimal value on this branch. If the monopolist had enough econometric measures allowing to precisely estimate the relevant parameters, he should post an introductory price just below $p^* = h + \hat{p}_L(j)$, so that η would match the single Nash equilibrium existing for the demand, which for these parameters lies on the high- η^d branch. Clearly, this is possible only if $h > -\hat{p}_L$, as in figures 9(b) and (d), but not in the case of figure 9(f) because h , the mean IWP, is too negative. Then, the monopolist would be able to drive smoothly the system to the point maximizing his profit, with slightly less demand and higher prices.

Alternatively, the monopolist may begin by posting the price that would maximize his profit if the customers did coordinate. For $\max\{h_{ch}(j), -\hat{p}_L(j)\} < h < h_M(j)$, coordination failure may occur, in which case the demand will find itself on the low- η suboptimal branch. The seller can then drive the population to the L boundary by smoothly decreasing the price until finding the point p^* . Upon a further small price reduction the fraction of buyers will suddenly jump to the high- η equilibrium. From that point on the price may be smoothly increased until reaching its optimal value on the high- η branch. As shown in Appendix A.5, the profit is a decreasing function of the price at the boundary L of the low demand branch: for $h > -\hat{p}_L(j)$ there is a maximum of the profit at η_L , the L boundary of the low- η branch — in particular for $h > h_-$, this is the unique maximum on this low- η branch (see Figure 8, dot-dashed line ($h = 0$), and Figure 9, (a) and (b)). This is not a Nash equilibrium since precisely if the price decreases below the value corresponding to this maximum the demand jumps to the high-demand manifold because the low- η^d equilibrium disappears. But this remark implies that, for $\max\{h_{ch}(j), -\hat{p}_L(j)\} < h < h_M$, if the population does not coordinate and the demand remains in the low- η^d branch, the monopolist may *increase* his profit by decreasing the price, driving the customers to the L boundary. In such case (Figure 8, $h = 0$), even without being aware of the existence of the high- η branch, starting from the low- η suboptimal branch with a relatively high posted price, a tâtonnement strategy with smooth modifications of the price may allow the monopolist drive the demand onto the high- η branch, and then reach the maximal profit. However, for $h_{ch}(j) < h < -\hat{p}_L(j)$, none of these scenarii may be implemented: in that case the L boundary is in the domain of negative values of \hat{p} (figures 9 (e) and (f)). Hence, the largest value of η that the monopoly may reach, even at a vanishing \hat{p} , lies inside the multiple demand region. Attracting enough customers to draw the system outside this region would require posting prices below the production cost. Under such conditions, that is if $h < -\hat{p}_L(j)$, neither the introductory pricing nor the tâtonnement strategy

are implementable: the risk due to the possibility of coordination failure cannot be avoided.

5.2 Minimax regret strategy

Recall that the high- η optimal solution is vulnerable not only because it requires coordination from the customers, but also due to its sensibility to small changes in the parameter values: this optimum lies at values of η very close to the U -boundary, that is the point where the branch of high- η demand disappears.

If the average willingness to pay is negative and the social interactions are strong enough, a suitable risk adverse policy should rely neither on the hypothesis that customers will coordinate, nor on the expectation that if coordination does occur, it will maintain itself. This is a least regret strategy where the monopoly posts the price corresponding to a sub-optimal profit, either with η_-^s buyers, i.e. the local maximum on the low- η^d branch, or a supply on the high- η -branch just outside the multi-valued domain (η slightly larger than η_L), whichever gives the highest profit – or is less risky.

In the first case, the restaurant is thus designed to have a low capacity. If the system's parameters lie in the region where customers have two equilibria (region with the double arrow in figure 6) and it happens that it becomes “in”, i.e. the customers coordinate on the high- η^d equilibrium, there will be a heavy demand, larger than the capacity, hence a queue for tables.

In the second case – admissible only if the L -boundary is in the domain of positive values of \hat{p}_- , the seller tries to keep the price at the value for which the demand jumped to the high- η branch, just outside the domain with multi-valued demand. If a change occurs in the population characteristics, so that the current posted price finds itself back into this domain, a failure in coordination can be cured by a small price decrease, finding again the L -boundary.

6 Conclusion

We analyzed the monopolist's profit optimization problem when there exist social influences among customers. We considered the generic case of finite variance distributions of the idiosyncratic willingness to pay (IWP) of the customers population. The model suggests possible explanations to the fact that prices of goods with bandwagon effects do not necessarily increase despite their success.

There are two critical (normalized) interaction strengths j_A and j_B whose precise values depend on the details of the IWP distribution. Depending on the strength j of the (normalized) social interactions the monopoly may be faced with three different situations: for $j < j_A$, the profit optimization gives a single price for each value of h , the (normalized) average willingness to pay of the population, and for the resulting posted price the demand is single valued. For $j > j_A$, there is a range of h values where the monopolist's profit presents two maxima. There is a first order transition where the optimal strategy shift from selling to few customers at a high price, to selling to a large fraction of customers at a low price. If $j_A < j < j_B$, since the customers system equilibrium in this region is a unique function of the price, the monopolist can drive the

market through the posted prices, and thus earn the maximum profit. The situation is very different for $j > j_B$ when the average willingness to pay is small enough – it may be smaller than the monopolist’s cost (i.e. $h < 0$). In this region, the customers meet a coordination problem and the monopolist cannot drive the market through prices alone. In addition, the price that is expected to give the largest profit is generically just below the critical value where the high demand disappears, implying the risk of a collapse of the demand from unexpected changes in the customers characteristics. Social interactions thus introduce uncertainty in the outcome of the monopolist strategy. In our discussion we presented different pricing strategies targeting the optimal or a suboptimal profit under these conditions.

The introductory pricing strategy discussed in section 5.2 is of the kind discussed by [11] and might be considered within the two-period pricing studied in [4]. This suggests another possible explanation for Becker’s restaurant pricing problem. If the restaurant determines its optimal price, and it happens to lie on the high- η^s branch, it will propose a number of tables proportional to η_+^s . If this equilibrium lies within the customers’ coordination region, posting the introductory price p^* will attract more customers than seats, with the corresponding queue at the entrance. Lasting of this situation reveals a precautionary risk dominant pricing strategy.

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A Appendices

A.1 Profit maximization

A.1.1 An effective supply function

There are different equivalent ways of performing the profit maximization when social interactions are present. One is to consider that η , and consequently the profit, are functions of p (as in [30]): $\eta = \eta^d(p)$, and $\pi(p) = p \eta^d(p)$; another one is to consider that p and the profit are functions of η , $p = p^d(\eta)$, and $\pi(\eta) = p^d(\eta) \eta$. Here we follow a reasoning that leads (obviously) to the same results, but deals symmetrically with the variables p and η . The interest of this approach is that it puts forward an analogy between the demand and the supply equations.

In order to maximize the monopolist’s profit, let us define

$$\Psi(\eta, p) \equiv p^d(\eta) - p. \quad (\text{A-1})$$

The equation $\Psi(\eta, p) = 0$ defines a curve Ψ in the plane $\{\eta, p\}$ along which π has to be maximized. Be

$$\mathbf{v}(\eta, p) \equiv (v_\eta, v_p) = (\partial\Psi/\partial p, -\partial\Psi/\partial\eta) \quad (\text{A-2})$$

a vector tangent to the curve $\Psi = 0$ at the point (η, p) .

The maximization of (11) along Ψ imposes that the directional derivative of π vanishes,

$$(\mathbf{v} \cdot \nabla) \pi \equiv v_\eta \frac{\partial\pi}{\partial\eta} + v_p \frac{\partial\pi}{\partial p} = 0, \quad (\text{A-3})$$

to guarantee that the profit is an extremum. If the maximum is reached inside the support of $\Gamma(\eta)$, it must also satisfy the second order condition

$$(\mathbf{v} \cdot \nabla) (v_\eta \frac{\partial \pi}{\partial \eta} + v_p \frac{\partial \pi}{\partial p}) \leq 0. \quad (\text{A-4})$$

For finite range pdfs (compact support), one has to check whether the maximum maximum lies on one of the boundaries of the support. Remark: had we chosen to consider η as a function of p , that is $\pi(p) = p\eta^d(p)$ as done in [30], this stability condition would read

$$\frac{d^2 \pi}{dp^2} \leq 0.$$

Introducing the components of \mathbf{v} given by equation (A-2)

$$v_\eta = \frac{\partial \Psi}{\partial p} = -1, \quad (\text{A-5})$$

$$v_p = -\frac{\partial \Psi}{\partial \eta} = -\frac{dp^d(\eta)}{d\eta}, \quad (\text{A-6})$$

into the first order condition (A-3) gives

$$p^d(\eta) = p^s(\eta) \quad (\text{A-7})$$

where $p^d(\eta)$ is the inverse demand given by equation (8), and

$$p^s(\eta) \equiv -\eta \frac{dp^d(\eta)}{d\eta}, \quad (\text{A-8})$$

which, making use of the expression (8) of p^d , is also given by

$$p^s(\eta) = -\eta \mathcal{D}'(j; \eta) = \eta[\Gamma'(\eta) - j]. \quad (\text{A-9})$$

Using (A-5), (A-6) and (A-8), the second order condition (A-4) reads

$$\left[-\frac{\partial}{\partial \eta} - \frac{dp^d(\eta)}{d\eta} \frac{\partial}{\partial p} \right] [-p + p^s(\eta)] \leq 0, \quad (\text{A-10})$$

and this can be rewritten as

$$\frac{d}{d\eta} [p^d(\eta) - p^s(\eta)] \leq 0. \quad (\text{A-11})$$

We may consider $p^s(\eta)$ given by (A-8) as an effective inverse supply function, although it is clearly not a true one, since it is defined by the monopolist's optimization program, itself based on the knowledge of the demand function. Nevertheless, it has all the properties of an inverse supply function, and the market equilibrium can be understood from the equality (A-7) between demand and (effective) supply. Note that from (A-8) the positivity of the supply price p^s is equivalent to having the inverse demand decreasing with η (or equivalently, from (A-9), to have the demand at a stable equilibrium, that is $\mathcal{D}'(j; \eta) \leq 0$).

A.1.2 Behavior of $\tilde{\Gamma}$

In order to have a full analogy between the Supply and Demand problems, one needs $\tilde{\Gamma}(\eta)$, defined by Eq (15), to be monotonically increasing from $-\infty$ to $+\infty$ when η goes from 0 to 1, and to have a single inflexion point. One can easily check that, for ‘usual’ pdfs such as the logistic or the Gaussian, $\tilde{\Gamma}$ is a monotonic, strictly increasing function of η for all $0 < \eta < 1$. For an arbitrary (smooth enough) pdf, one can show that $\tilde{\Gamma}$ is a monotonically increasing function for $\eta > \eta_B$, as well as for η small enough whenever the pdf has a finite variance. It remains the possibility to have a non monotonic behavior of $\tilde{\Gamma}$ in some small intermediate range, η not too small and not too close to η_B .

Let us now express the derivative of $\tilde{\Gamma}$ in term of the pdf $f(x)$ and its cumulative $G(x) \equiv 1 - F(x)$. One has $\eta = G(x)$. From the definition of $\tilde{\Gamma}$, one has

$$\frac{d\tilde{\Gamma}}{d\eta} = -2 \frac{dx}{d\eta} - G(x) \frac{d^2x}{d\eta^2}.$$

Now $\frac{dx}{d\eta} = 1/G'(x)$, and thus $\frac{d^2x}{d\eta^2} = -\frac{G''}{G'^3}$. It follows that one can write

$$\frac{d\tilde{\Gamma}}{d\eta} = -\frac{G^3}{G'^3} \left[-\frac{G''}{G^2} + 2\frac{G'^2}{G^3} \right] = -\left[\frac{G}{G'}\right]^3 \left[\frac{d^2}{dx^2} \frac{1}{G(x)} \right]$$

which means

$$\frac{d\tilde{\Gamma}}{d\eta} = \left[\frac{1 - F(x)}{f(x)} \right]^3 \left[\frac{d^2}{dx^2} \frac{1}{1 - F(x)} \right] \quad (\text{A-12})$$

The right hand side is positive if and only if

$$\frac{d^2}{dx^2} \frac{1}{1 - F(x)} > 0. \quad (\text{A-13})$$

Hence $\tilde{\Gamma}$ is a monotonic, strictly increasing function of η for all $0 < \eta < 1$ iff the above property is true for every x belonging to the support of f .

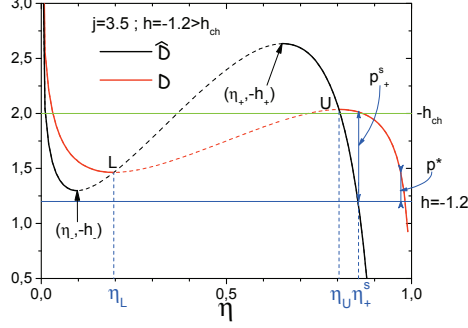
This condition (A-13) is not a very stringent one. After some algebra it may be shown that it is equivalent to impose that, *in the absence of externalities* ($j = 0$), the demand satisfies

$$\frac{d^2}{dp^2} \frac{1}{\eta^d(p)} > 0. \quad (\text{A-14})$$

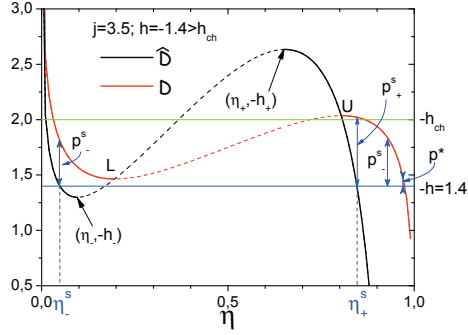
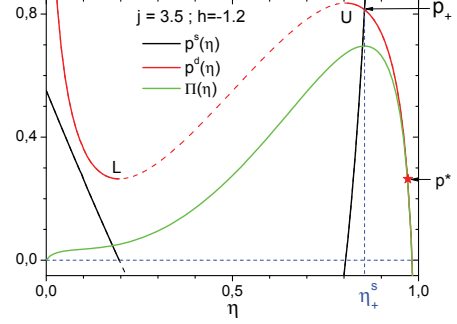
This is a weaker condition than a convexity condition, $d^2 \log \eta^d(p)/dp^2 < 0$, frequently assumed in economics.

A.2 Numerical illustrations

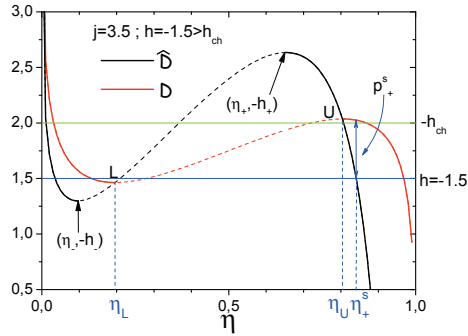
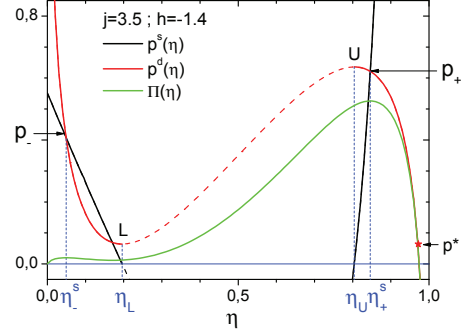
Figures 9 present examples of possible situations met by the monopoly. They correspond to systems with parameters $j = 3.5 > j_B$ (for the logistic, $j_B \approx 2.21$) and the three different values of h , indicated on figure 4, that fall within the region of uncertain outcome for the η_+^s strategy. The curves \mathcal{D} and $\tilde{\mathcal{D}}$ on Figures (a), (c) and (e) are typical of any smooth pdf in the region with multiple solutions of the profit optimization. They show the constructions allowing to determine the optimal prices. The lines $y = -h_{ch}$



(a) & (b)



(c) & (d)



(e) & (f)

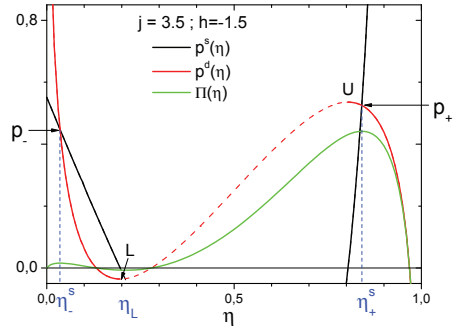


Figure 9: Figures (a), (c) and (e): functions $\mathcal{D}(j;\eta)$ and $\tilde{\mathcal{D}}(j;\eta)$. The construction that determines the profit extrema is illustrated. Figures (b), (d) and (f): price and profit vs. η showing the extrema of π . When $h > h_{ch} \approx -2$: the large- η strategy is the optimum. The dotted lines correspond to the non-economic demand between η_L and η_U , where \mathcal{D} has positive slope.

are represented: for the values of h considered the optimal strategy corresponds to the high- η^s branch. Optimal prices are given by the difference $\mathcal{D} - \tilde{\mathcal{D}}$ at the value of η where the line $y = -h$ intersects the curve $\tilde{\mathcal{D}}$. The introductory price p^* is indicated whenever it is viable (i.e. positive). In particular, when $h = -1.5$ introductory prices allowing to get rid of the coordination problem do not exist. Figures (b), (d) and (f) present the corresponding demand and supply prices, $p^d = h + \mathcal{D}$ and p^s (the optimal price corresponds to $p^s = p^d$), and the profits $\pi = \eta p^s$. In (a,b) the only optimal strategy is η_+^s . In (c,d) both strategies η_-^s and η_+^s fall inside the multi-valued demand region. The profit of targeting η_-^s , which does not need coordination, is smaller than the profit corresponding to the introductory price p^* , and the latter may allow to drive the system to the η_+^s equilibrium of optimal profit. If $h = -1.5$, figures (e,f), both strategies fall in the coordination region, and there is no possibility to get rid of the problem through introductory prices.

A.3 Monopolist's Phase Diagram: Details

A.3.1 Domain of multiple pricing strategies

Like for the demand, there is for the supply a bifurcation at critical value of j defined by

$$j_A = \tilde{\Gamma}'(\eta_A)/2, \quad \text{with} \quad \eta_A \equiv \arg \min_{\eta} \tilde{\Gamma}'(\eta), \quad (\text{A-15})$$

beyond which there are multiple solutions for the supply. One can show that $\eta_A \leq \eta_B$ and $j_A \leq j_B$.

If $j < j_A$ both curves \mathcal{D} and $\tilde{\mathcal{D}}$ are monotonically decreasing functions of η . Equation (12) has a single solution η^s for each couple j, h . Given any $j (< j_A)$, if h increases continuously from a very small value (highly negative) to a large positive one, the optimal price –which by (16) is the difference between \mathcal{D} and $\tilde{\mathcal{D}}$ – decreases and the fraction of buyers increases, both monotonically.

For $j \geq j_A$, there is a finite range of values of h where $\tilde{\mathcal{D}}(j; \eta)$ presents two extrema: a minimum at $\eta_-(j) < \eta_A$ and a maximum at $\eta_+(j) > \eta_A$. They satisfy $\tilde{\mathcal{D}}'(j; \eta_{\pm}) = 0$. Correspondingly, the profit presents two relative maxima at the intersections of $y = -h$ with the branches of $\tilde{\mathcal{D}}(j; \eta)$ that have negative slope. Notice that the additional intersection at an intermediate value of η with the branch having $\tilde{\mathcal{D}}'(j; \eta) > 0$ corresponds to a *minimum* of the profit. The profit's absolute maximum has to be determined numerically, through comparison of the profit relative maxima.

As an example, plots of $\tilde{\mathcal{D}}(j; \eta)$ and $\mathcal{D}(j; \eta)$ for a logistic pdf and a value $j > j_B$ are presented on Figure 9. We have explicitly indicated the values of $\mathcal{D}(j; \eta)$ corresponding to the unstable equilibria $\eta \in [\eta_L(j), \eta_U(j)]$. The price construction for a particular value of h is exhibited.

The values of $\eta_+(j)$ and $\eta_-(j)$ are determined following the same steps as for the customer's model, and have the same form as equations (10) which define $\eta_L(j)$ and $\eta_U(j)$, but with $\tilde{\Gamma}(\eta)$ and \hat{j} instead of $\Gamma(\eta)$ and j respectively. Introducing the values $\eta_+(j)$ and $\eta_-(j)$ into (12) we obtain:

$$h_{\pm}(j) = -\tilde{\mathcal{D}}(j; \eta_{\pm}(j)). \quad (\text{A-16})$$

In the plane $\{j, h\}$ the lines $h = h_+(j)$ and $h = h_-(j)$ represented on figure 4 are the boundaries of a region where the profit has multiple (sub)optima. These boundaries merge at the point A that satisfies simultaneously $\tilde{\mathcal{D}}'(j; \eta) = 0$, and $\tilde{\mathcal{D}}''(j; \eta) = 0$, that is

$$A \equiv \{j_A, h_A \equiv \tilde{\Gamma}(\eta_A) - \eta_A \tilde{\Gamma}'(\eta_A)\}. \quad (\text{A-17})$$

It may be easily checked that $d[h_-(j) - h_+(j)]/dj = 2[\eta_+(j) - \eta_-(j)]$, meaning that, like in the customers problem, the width of the region with multiple extrema increases with j because $\eta_- < \eta_+$.

A.3.2 Null price boundary

When $j > j_B$ both \mathcal{D} and $\tilde{\mathcal{D}}$ present positive slopes, but for different ranges of η . As already stated, both curves cross each other at η_L and η_U , with $\tilde{\mathcal{D}}'(\eta_L) > 0$ and $\tilde{\mathcal{D}}'(\eta_U) < 0$. Thus, at η_L the profit is a minimum. Since $\eta_- < \eta_L$, for any $\eta^s < \eta_-$, $\tilde{\mathcal{D}} < \mathcal{D}$: the optimal prices of the low- η^s strategies are positive in all the range of $\{h, j\}$ values for which it exists.

In contrast, at the other side of the customers' unstability gap $[\eta_L, \eta_U]$, $\tilde{\mathcal{D}}(\eta_U) = \mathcal{D}(\eta_U)$ and since $\eta_+ < \eta_U$, the boundary of the high- η^s strategy (at $h = h_+(j)$) corresponds to a *negative* price. Notice that in the range $\eta_+ < \eta^s < \eta_U$ where the monopolist's relative maximum has a negative price, the customers demand is unstable and is not expected to exist at equilibrium. Thus an equilibrium with high demand only exists for $\eta > \eta_U(j)$. The line $h = h_U(j)$ is the null-price line (that is actually the line where $P = C$) on the high- η manifold: it sets a lower bound to the values of h for which the monopolist's high- η strategy is viable.

A.3.3 Bifurcation point B

In the plane $\{j, h\}$ the point B defined by:

$$B \equiv \{j_B, h_B \equiv -\hat{p}_B\}, \quad (\text{A-18})$$

is analogous to the point B defined for the customers phase diagram (see Section 2). It belongs both to the line $h_+(j)$ and to the null-price line. The corresponding fraction of buyers is η_B . In the Appendix, section A.3.4 we study with some details the vicinity of the singular points A and B in the monopolist's phase diagram.

A.3.4 Vicinity of the singular points A and B

The bifurcation point A plays the same role, in the monopolist's phase diagram, as the bifurcation B in the Demand phase diagram [30, 20]. The singular behaviour at this apex A is obtained in the very same way. Developing in the vicinity of the A , at which $\tilde{\Gamma}''(\eta_A) = 0$, we obtain expressions for the boundaries of the multiple extrema region that are similar to those of the demand phase diagram, but with $\tilde{\Gamma}$ in the place of Γ , \hat{j} instead of j and $\hat{\epsilon} \equiv 2\epsilon$ instead of ϵ .

It is interesting to consider more in details the vicinity of the (monopolist's) point B , where one has both $p = 0$ and marginal stability for the '+' solution. Near B , for

$j > j_B$ and/or $h > h_B$, the ‘+’ solution gives a small price value, and a value of η close to η_B . Like for the demand [20], we can expect a similar behaviour for the monopolist’s solution: a linear increase of the price and a singular, square root, behaviour for η . Indeed at first non trivial order in ϵ one gets

$$\text{for } j = j_B, 0 < \epsilon \equiv h - h_B < 1 : \begin{cases} p_+ &= \epsilon, \\ \eta_+ &= \eta_B + \sqrt{\frac{2}{\eta_B \Gamma'''(\eta_B)}} \epsilon^{1/2}, \\ \Pi_+ &= \eta_B \epsilon + \sqrt{\frac{2}{\eta_B \Gamma'''(\eta_B)}} \epsilon^{3/2} \end{cases} \quad (\text{A-19})$$

And similarly,

$$\text{for } h = h_B, 0 < \epsilon \equiv j - j_B < 1 : \begin{cases} p_+ &= \eta_B \epsilon \\ \eta_+ &= \eta_B + \sqrt{\frac{2}{\Gamma'''(\eta_B)}} \epsilon^{1/2}, \\ \Pi_+ &= \eta_B^2 \epsilon + \eta_B \sqrt{\frac{2}{\Gamma'''(\eta_B)}} \epsilon^{3/2} \end{cases} \quad (\text{A-20})$$

The ‘+’ solution appears at B through a continuous transition for the profit Π , with a discontinuous jump for η (from 0 to η_B), and then a square-root behaviour. The latter is specific to the point B . Indeed, one can perform a similar expansion in the vicinity of the null price line.

Consider a point on this line with $j > j_B$. The corresponding value of η is the solution $\eta_0(j)$ of $j = j_0(\eta)$, and the value of h is $h_0(j) \equiv h_0(\eta_0(j))$. Then for $h = h_0(j) + \epsilon$, $0 < \epsilon < 1$, expansion of $p = p^s(\eta) = p^d(\eta)$ at first non trivial order in ϵ gives

$$\text{for } j > j_B, 0 < \epsilon \equiv h - h_0(j) < 1 : \begin{cases} p_+ &= \epsilon, \\ \eta_+ &= \eta_0(j) + \frac{\epsilon}{\eta_0(j) \Gamma''(\eta_0(j))}, \\ \Pi_+ &= \eta_0(j) \epsilon + \frac{\epsilon^2}{\eta_0(j) \Gamma''(\eta_0(j))}, \end{cases} \quad (\text{A-21})$$

One sees on the above expansion for η how the singular behaviour at $j = j_B$ appears: as j approaches j_B^+ , $\eta_0(j) \rightarrow \eta_B$, hence $\Gamma''(\eta_0(j))$ tends to zero, and thus the coefficient of ϵ in the expansion of η diverges.

A.3.5 Correspondence between the demand and the supply branches

The fact η_-^s and η_+^s , the low- η and large η solutions for the seller, do correspond to η values falling on, respectively, the low- η and large η branches of the demand, is shown more formally here.

Any solution η_-^s corresponding to the low- η branch for the supply lies also on the low- η branch of the demand, because $\eta_-^s < \eta_- < \eta_L$ (see the left-hand side figures 9).

Similarly, since the zero-price line corresponds to $h_0(j) = -\hat{p}_U(j)$, any viable (that is with $p^s \geq 0$) solution η_+^s on the high- η branch for the seller also lies on the high- η branch of the demand, i.e. $\eta_+^s \geq \eta_U$.

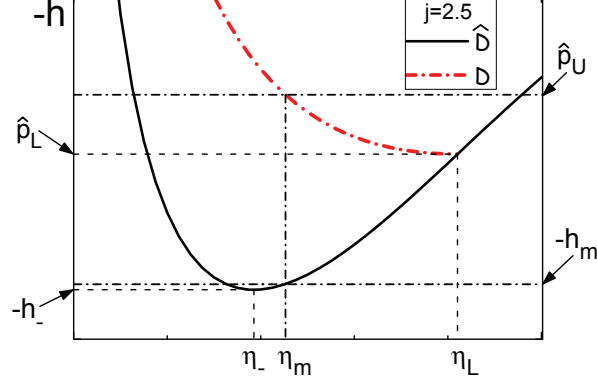


Figure 10: *Supply phase diagram: details of the low- η strategy*

A.4 Monopolist's low- η branch

One can make the analysis of the low- η branch more precise. Let us define $\eta_m(j) < \eta_L(j)$ such that

$$\mathcal{D}(j; \eta_m) = \hat{p}_U(j), \quad (\text{A-22})$$

which is the low- η demand at the border $\hat{p}_U(j)$ of the customers' multiple equilibria region. For $\eta_m < \eta < \eta_L$ the customers low- η equilibrium coexists with the one at large- η . Be

$$h_m(j) \equiv -\tilde{\mathcal{D}}(j, \eta_m) = -\hat{p}_U(j) - \eta_m \mathcal{D}'(j; \eta_m). \quad (\text{A-23})$$

Depending on j , $\eta_m(j)$ may be smaller or larger than $\eta_-(j)$. Be $j_C (> j_B)$ the value of j for which these two values of η are equal: $\eta_m(j_C) = \eta_-(j_C)$ and consequently $h_C \equiv h_m(j_C) = h_-(j_C)$. It verifies

$$\mathcal{D}(j; \eta_m(j_C)) - \tilde{\mathcal{D}}(j; \eta_m(j_C)) = \hat{p}_U(j_C) + h_-(j_C). \quad (\text{A-24})$$

In words, j_C is the value of j at which the (low- η^s) optimal strategy corresponds to a fraction of buyers η_- and the corresponding price is exactly equal to $\hat{p}_U(j_C) + h_-(j_C)$.

If $j > j_C$, $\eta_m < \eta_-$. Then, for $h_m < h < h_-$ the (low- η^s) relative maximum lies at η_-^s with $\eta_m < \eta_-^s < \eta_-$, i.e. inside the region with $\hat{p}_L < \mathcal{D} < \hat{p}_U$, where the customers' system has multiple equilibria. As shown in Appendix A.5, this maximum never gives the absolute maximum of the profit, which will be on the high- η branch. In particular one can thus conclude that the high- η strategy becomes optimal before h reaches h_m , that is

$$h_{ch}(j) < h_m(j). \quad (\text{A-25})$$

In addition to the η_-^s solutions, if $h_m < -\hat{p}_L$ there exists the relative maximum at the margin η_L of the multiple equilibria region. Although it does not correspond to an optimal pricing strategy, for completeness let us point out that this end point becomes

a minimum for $j > j_D$ defined by

$$h_D \equiv h_m(j_D) = -\hat{p}_L(j_D), \quad (\text{A-26})$$

because for larger values of j , $h_m < -\hat{p}_L$.

To summarize, for $j < j_C$ and $h < h(j)$ the low- η^s optimal strategy the low- η^s strategy $j_C < j < j_D$) and $h > h_m$ the profit has a minimum at the boundary η_L whereas for $j > j_D$.

Figure 10 summarizes the results for the low- η manifold in the case of a logistic distribution.

A.5 Behavior of the profit near the boundaries

In addition to maxima obtained from the solutions of the 1st and 2nd order equations, as discussed above, there may exist maxima of the profit at extreme (boundary) values: the profit $\pi(p)$ may have a (possibly local) maximum at some of the boundary values, $p = 0$, $p = \infty$, and, in the domain of h and j values for which the demand $\eta^d(p)$ has two branches, at the maximal value $p_U = h + \hat{p}_U(j)$ for which the high- η demand exists, and the minimal value $p_L = \max(0, h + \hat{p}_L(j))$ for which the low- η demand exists. Let us consider the behavior of the profit $\pi(p) = p\eta^d(p)$ as a function of the price p .

A.5.1 Behavior of the profit near $p = 0$ and near $p = \infty$

One can check that, for IWP distributions with no fat tail⁷ (that is with finite variance σ), the profit is decreasing to 0 as p goes to ∞ : the large p limit is always a minimum of the profit.

From the definition of the profit as $\pi(p) = p\eta^d(p)$, one has

$$\frac{d\pi}{dp} = \eta^d(p) + p \frac{d\eta^d}{dp} \quad (\text{A-27})$$

Hence at $p = 0$ one has $\frac{d\pi}{dp} = \eta > 0$: this boundary is always (unsurprisingly) a minimum of the profit.

A.5.2 End points of the high and low η branches

For $j > j_B$, the demand has two branches, η_L^d and η_U^d , hence the function $\pi(p)$ has itself two branches (see Figure 8) which we denote by π_L and π_U respectively. Necessarily, at least one maximum of the profit exists on each branch.

If $h + \hat{p}_L(j) < 0$, that is when the low- η branch of the demand exists already at $p = 0$, the above argument for the boundary $p = 0$ applies: the profit increases along this branch when p is increased from $p = 0$ (going through a maximum at some $p > 0$ before decreasing to zero as $p \rightarrow \infty$).

⁷In the case of a distribution with a fat tail, one can show that for a population of N customers, with N large but finite, a maximum of the profit is obtained by selling a single unit of the good ($\eta = 1/N$) at the customer with the largest willingness to pay, the price being then (at least) of order N .

Now we know that the derivative of the demand at each one of the boundaries, $\hat{p}_U(j) \equiv \mathcal{D}(j; \eta_U(j))$ and $\hat{p}_L(j) \equiv \mathcal{D}(j; \eta_L(j))$, is singular, $\frac{d\eta^d(p)}{dp} = -\infty$ (since $\frac{dp^d(\eta)}{d\eta} = 0$, and the demand decreases with p). It follows that, for $h > -\hat{p}_U(j)$, at $p_U = h + \hat{p}_U(j)$, $\frac{d\pi_U}{dp} = -\infty$, and for $h > -\hat{p}_L(j)$, at $p_L = h + \hat{p}_L(j)$, $\frac{d\pi_L}{dp} = -\infty$. Hence the boundary on the high- η branch, p_U , is always a minimum of the profit, whereas for $h > -\hat{p}_L(j)$, p_L is always a maximum of the profit on the low- η branch of the demand. Remark: for $h < h_m$, on the low η branch there is a maximum for some price greater than p_L : increasing the price from p_L , the profit decreases, goes through a minimum, increases up to a maximum and decreases again, going to zero as $p \rightarrow \infty$.

A.5.3 Non optimality of the low- η profit for $p_L \leq p \leq p_U$

The maximum of π_L at p_L for $h > -\hat{p}_L(j)$, however, is always a (strictly) *local* maximum, as it is the case for *any* maximum of the profit that would exist on the low- η branch of the demand for a price $p_L \leq p \leq p_U$.

Indeed, consider a value p in this range, $p_L \leq p \leq p_U$. For this price the demand has two possible values, $\eta_L^d(d)$ on the low- η branch (with $d = p - h$), and $\eta_U^d(d)$ on the high- η branch. Since $\eta_L^d(d) < \eta_U^d(d)$, the profit $p\eta_L^d(d)$ is strictly smaller than $p\eta_U^d(d)$, that is the profit for the same price obtained with the high-demand, and the later is itself smaller (or equal) to the maximal profit associated to the high- η branch.

In the range $h_+ < h < h_-$, an alternative way to see the fact that the profit at p_L is never the optimal one is the following, for smooth enough pdfs. The profit $\Pi(\eta)$ is a continuous function of η with two relative maxima, one at $\eta < \eta_-$, the other at $\eta > \eta_+$, and a minimum in between. One can show that $\eta_- < \eta_L < \eta_+$, that is $\mathcal{D}(j; \eta)$ hits $\tilde{\mathcal{D}}(j; \eta)$ at a value η_L where $\tilde{\mathcal{D}}$ is increasing with η . Indeed, at $\eta = \eta_L$, $\mathcal{D}' = 0$, hence $\tilde{\mathcal{D}}' = \eta_L \mathcal{D}''$, and $\mathcal{D}''(j; \eta_L) = -\Gamma''(\eta_L) > 0$ (Γ is concave on $[0, \eta_B]$, see [20]). Since $\eta_- < \eta_L < \eta_+$, η_L is in between the two maxima, so that the profit is always lower at η_L than at the global maximum (the largest of the two relative maxima).

In addition, the maximum of the profit at p_L is not a Nash equilibrium: any small deviation of price below the value p_L would make the demand jump on the high-demand branch.

In conclusion, there is no optimal strategy for the seller corresponding to prices at the boundaries. We have also seen that the low- η profits, when obtained with a price in the coexistence domain, never give an absolute maximum of the profit (see Figure 8 for an example).

A.5.4 Non optimality of the low- η profit at $\eta = \eta_L$

If $-\hat{p}_L < h < h_-$, since $\eta_- < \eta_L$, there are two intersections of $y = -h$ with $y = \tilde{\mathcal{D}}(j; \eta)$, one at $\eta_-^s < \eta_-$ where $\tilde{\mathcal{D}}$ has negative slope, the other at a larger value of η where $\tilde{\mathcal{D}}' > 0$. Only the first one corresponds to a relative maximum of the profit, the other one is a minimum. If η is increased beyond this minimum, the profit increases continuously and reaches a relative maximum at η_L . This relative maximum does not satisfy the conditions (12) and (13) because it lies at the border of the domain $\eta \in [0, \eta_L]$ where the low- η customers' equilibrium exists. The corresponding price is $p^s = h + \hat{p}_L > 0$,

so that the profit is $\pi(\eta_L) = \eta_L(h + \hat{p}_L)$. If $\pi(\eta_L) > \pi(\eta_-^s)$ the absolute maximum of the profit lies in the high- η^s branch, because the profit is a monotonically increasing function of η from the minimum at $\eta < \eta_L$ up to its maximum at $\eta_+^s > \eta_L$, reached on the high- η branch where $\tilde{\mathcal{D}}'(j; \eta) > 0$. Conversely, if $\pi(\eta_L) < \pi(\eta_-^s)$ the absolute maximum is at either η_-^s or η_+^s but clearly not at η_L . In other words, the extremum at the boundary η_L is never a winning strategy and the monopolist should never post the corresponding price. For smaller values of h , $h < -\hat{p}_L$ the slope of $\tilde{\mathcal{D}}(j; \eta)$ for $\eta \in [0, \eta_L]$ is negative: there is no possible maximum at the border η_L . For these values of h again there is a single optimum on the low- η^s branch, at η_-^s .