# Turbulence Navier Stokes and Symmetries



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- Symmetry in fields and in equations
- Symmetries of the Navier Stokes
- Breaking of symmetries

#### Flow behind a cylinder



## Symmetries of Fields

We will say that a field  $\mathbf{u}(\mathbf{x},t)$  is invariant under a transformation  $\mathcal{T}$  or that it has a  $\mathcal{T}$ -symmetry if under the act of the transformation it remains the same:

$$\mathcal{T}[\mathbf{u}] = \mathbf{u}$$



# Space translations

$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \mathbf{u}(\mathbf{x} + \hat{\mathbf{e}}_i \ell, t)$$



$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \mathbf{u}(\mathbf{x},t+T)$$

- Time periodic flows have discrete symmetries
- Constant in time flows have continuous symmetries

# Reflections

$$\begin{split} \mathcal{T}[(u_x(x,y,z,t),u_y(x,y,z,t),u_z(x,y,z,t))] = \\ (-u_x(-x,y,z,t),u_y(-x,y,z,t),u_z(-x,y,z,t)) \end{split}$$

• 
$$\mathbf{u}(\mathbf{x},t) = (\sin(x)\cos(y), -\cos(x)\sin(y), 0)$$



#### Rotations

$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \mathcal{R}\mathbf{u}(\mathcal{R}^{-1}\mathbf{x},t) + \mathbf{c}$$

Where  ${\mathcal R}$  is the rotation matrix  ${\mbox{\bf Example:}}$ 

• 
$$\mathbf{u}(\mathbf{x},t) = (y, -x, 0)$$



## Galilean Transformations

$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \mathbf{u}(\mathbf{x} + \mathbf{c}t, t) + \mathbf{c}$$

• 
$$\mathbf{u}(\mathbf{x},t) = -x/t$$

# Scalling Transformations

$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \lambda^{\alpha} \mathbf{u}(\lambda \mathbf{x},t)$$

• 
$$\mathbf{u}(\mathbf{x},t) = (y, -x, 0)(x^2 + y^2)^{\alpha/2 - 1}$$



#### Symmetries of equations

We will say that an equation (e.g. the Navier-Stokes) is invariant under a transformation  $\mathcal{T}$  or that it has a  $\mathcal{T}$ -symmetry if for any solution  $\mathbf{u}(\mathbf{x},t)$  of this equation  $\mathcal{T}[\mathbf{u}(\mathbf{x},t)]$  is also a solution.

Note that  $\mathbf{u}(\mathbf{x},t)$  does not have to be a symmetric field.



## Symmetries of equations

**Lemma:** If the initial conditions  $\mathbf{u}(\mathbf{x}, 0)$  has one of the spatial symmetries of the Navier-Stokes  $\mathcal{T}[\mathbf{u}(\mathbf{x}, 0)] = \mathbf{u}(\mathbf{x}, 0)$ , then if  $\mathbf{u}(\mathbf{x}, t)$  remains smooth it retains this symmetry for all times.  $\mathcal{T}[\mathbf{u}(\mathbf{x}, t)] = \mathbf{u}(\mathbf{x}, t)$ 

**Proof:** If  $\mathbf{u}(\mathbf{x},t)$  is a solution then (since  $\mathcal{T}$  is one of the symmetries of the Navier-Stokes)  $\mathcal{T}[\mathbf{u}(\mathbf{x},t)]$  is also a solution that has the same initial conditions as  $\mathbf{u}(\mathbf{x},t)$  ( $\mathcal{T}[\mathbf{u}(\mathbf{x},0)] = \mathbf{u}(\mathbf{x},0)$ ). Thus either there is non-uniqueness of solutions or

$$\mathcal{T}[\mathbf{u}(\mathbf{x},t)] = \mathbf{u}(\mathbf{x},t).$$

(Non-uniqueness occurs only for non-smooth  $\mathbf{u}(\mathbf{x}, t)$ ).

• Space translations: 
$$x' = x + \ell$$

• "if  $\mathbf{u}(\mathbf{x},t)$  is a solution  $\mathbf{u}(\mathbf{x}+\ell,t)$  is also a solution."

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• 
$$\partial_x \mathbf{u}(\mathbf{x}+\ell,t) = \frac{\partial x'}{\partial x} \partial_{x'} \mathbf{u}(\mathbf{x}',t) = \partial_{x'} \mathbf{u}(\mathbf{x}',t)$$

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$$\partial_x \mathbf{u}(\mathbf{x}+\ell,t) = \frac{\partial x'}{\partial x} \partial_{x'} \mathbf{u}(\mathbf{x}',t) = \partial_{x'} \mathbf{u}(\mathbf{x}',t)$$

$$\partial_t \mathbf{u}(x+\ell,t) + \mathbf{u}(x+\ell,t) \cdot \nabla \mathbf{u}(x+\ell,t) = -\nabla P + \nu \nabla^2 \mathbf{u}(x+\ell,t) + \mathbf{f}(\mathbf{x},t)$$
$$\partial_t \mathbf{u}(x',t) + \mathbf{u}(x',t) \cdot \nabla' \mathbf{u}(x',t) = -\nabla' P + \nu {\nabla'}^2 \mathbf{u}(x',t) + \mathbf{f}(\mathbf{x}'-\ell,t)$$

which is the original Navier Stokes (if  $f(x, t) = f(x + \ell, t)$ )

 $ie, \ \mathbf{u}(x+\ell,t)$  satisfies the same equations as  $\mathbf{u}(x,t)$ 

- Space translations:  $x' = x + \ell$
- Time translations: t' = t + T
  - "if  $\mathbf{u}(\mathbf{x},t)$  is a solution  $\mathbf{u}(\mathbf{x},t+T)$  is also a solution."

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$$\partial_t \mathbf{u}(\mathbf{x}, t+T) = \frac{\partial t'}{\partial t} \partial_{t'} \mathbf{u}(\mathbf{x}, t') = \partial_{t'} \mathbf{u}(\mathbf{x}, t')$$

- Space translations:  $x' = x + \ell$
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- Galilean transformations:  $\mathbf{x}' = \mathbf{x} \mathbf{c}t$ , t' = t,  $\mathbf{u}' = \mathbf{u} + \mathbf{c}$ 
  - "if  $\mathbf{u}(\mathbf{x},t)$  is a solution  $\mathbf{u}(\mathbf{x}-\mathbf{c}t,t)+\mathbf{c}$  is also a solution."

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• 
$$\partial_t (\mathbf{u}(\mathbf{x} - \mathbf{c}t, t) + \mathbf{c}) = \left(\frac{\partial t'}{\partial t}\right) \partial_{t'} \mathbf{u}(\mathbf{x}', t') + \left(\frac{\partial \mathbf{x}'}{\partial t}\right) \nabla_{\mathbf{x}'} \mathbf{u}(\mathbf{x}', t')$$

• 
$$\partial_t \mathbf{u}(\mathbf{x}',t') = \partial_{t'} \mathbf{u}(\mathbf{x}',t') - \mathbf{c} \nabla' \mathbf{u}(\mathbf{x}',t')$$

- Space translations:  $x' = x + \ell$
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- $\bullet$  Galilean transformations:  $\mathbf{x}' = \mathbf{x} \mathbf{c} t, \ t' = t, \ \mathbf{u}' = \mathbf{u} + \mathbf{c}$ 
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• 
$$(\mathbf{u} + \mathbf{c}) \cdot \nabla(\mathbf{u} + \mathbf{c}) = \mathbf{u} \cdot \nabla \mathbf{u} + \mathbf{c} \cdot \nabla \mathbf{u}$$

$$\partial_t \mathbf{u}' + \mathbf{u}' \cdot \nabla \mathbf{u}' = -\nabla P + \nu \nabla^2 \mathbf{u}' + \mathbf{f}$$
$$\partial'_t \mathbf{u}' - \mathbf{c} - \nabla' \mathbf{u} + \mathbf{u} \cdot \nabla' \mathbf{u} + \mathbf{c} - \nabla' \mathbf{u} = -\nabla' P + \nu {\nabla'}^2 \mathbf{u} + \mathbf{f}$$
if  $\mathbf{f}(\mathbf{x}, t) = \mathbf{f}(\mathbf{x} - \mathbf{c}t, t)$ 

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- Parity (reflections):  $\mathbf{u}' = -\mathbf{u}$ ,  $\mathbf{x}' = -\mathbf{x}$ 
  - "if  $\mathbf{u}(\mathbf{x},t)$  is a solution  $-\mathbf{u}(-\mathbf{x},t)$  is also a solution."

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- Scaling  $\mathbf{x}' = \mathbf{x}/\lambda$ ,  $t' = t/\lambda^{\alpha}$ ,  $\mathbf{u}' = \lambda^{\beta}\mathbf{u}$ 
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$$\lambda^{\beta-\alpha}\partial_t \mathbf{u} + \lambda^{2\beta-1}\mathbf{u}\cdot\nabla'\mathbf{u} = -\lambda^{2\beta-1}\nabla P + \nu\lambda^{\beta-2}\nabla^2\mathbf{u} + \mathbf{f}$$

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Is a solution if  $\beta-\alpha=2\beta-1$  and  $2\beta-1=\beta-2$ 

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Is a solution if  $\beta-\alpha=2\beta-1$  and  $2\beta-1=\beta-2$   $\beta=-1$  and  $\alpha=2$ 

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Is a solution if  $\beta - \alpha = 2\beta - 1$  and  $2\beta - 1 = \beta - 2$  $\beta = -1$  and  $\alpha = 2$ In the absence of viscosity there is a scaling symmetry for any  $\beta$ and  $\alpha = 1 - \beta$ 

- If  $\mathbf{u}(\mathbf{x},0)$  has one of the spatial symmetries of the Navier Stokes equations then  $\mathbf{u}(\mathbf{x},t)$  will retain this symmetry at all times
- Most of the symmetries of the Navier Stokes equations break down when non-constant forcing is considered
- Most of the symmetries of the Navier Stokes equations break down when non-infinite domain sizes are considered

# Thank you for your attention!