

# Rare transitions to thin-layer turbulent condensates

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Turbulent flows in a thin layer can develop an inverse energy cascade leading to spectral condensation of energy when the layer height is smaller than a certain threshold. These spectral condensates take the form of large-scale vortices in physical space. Recently, evidence for bistability was found in this system close to the critical height: depending on the initial conditions, the flow is either in a condensate state with most of the energy in the two-dimensional (2-D) large-scale modes, or in a three-dimensional (3-D) turbulent state with most of the energy in the small scale modes. This bistable regime is characterised by the statistical properties of random and rare transitions between these two locally stable states. Here, we examine these statistical properties in thin-layer turbulent flows, where the energy is injected by stochastic and deterministic forcing. To this end, by using a large number of direct numerical simulations (DNS), we measure the decay time  $\tau_d$  of the 2-D condensate to 3-D turbulent state and the build-up time  $\tau_b$  of the 2-D condensate. We show that both of these times  $\tau_d, \tau_b$  follow an exponential distribution with mean values that increase faster than exponentially as the layer height gets closer to the threshold. We further show that the dynamics of large-scale kinetic energy may be modeled by a stochastic Langevin equation. From time-series analysis of DNS data, we determine the effective potential that shows two minima corresponding to the 2-D and 3-D states when the layer height is close to the threshold.

**Key words:** Turbulence, Stochastic Processes

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## 1. Introduction

Turbulence is ubiquitous in the universe, from stars to tea cups. Many astrophysical and geophysical turbulent flows, such as planetary oceans and atmospheres, are subject to geometrical constraints, e.g. thinness in one spatial direction (Pedlosky 2013). Such constraints significantly change the properties of the flow, which therefore deviate from those of classical three-dimensional (3-D) homogeneous and isotropic turbulence. Fully 3-D turbulence is characterised by a forward cascade of energy from large to small scales (Frisch 1995), while in two dimensions (2D), an inverse energy cascade from small to large scales occurs due to additional inviscid invariants such as enstrophy (Boffetta & Ecke 2012). Turbulence in thin layers combines properties of both cases, as large-scale dynamics are constrained to be 2-D, whereas small scale dynamics are not. As a

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consequence, in thin-layer turbulence, energy may cascade both to small and large scales depending on the layer height  $H$ : Above a critical height  $H_c$  there is no inverse cascade while below this critical height an inverse cascade develops with its amplitude (measured by the inverse energy flux) increasing continuously. Similar transitions towards an inverse cascade occur in rotating turbulence stratified turbulence magnetohydrodynamic systems (see the review articles (Alexakis & Biferale 2018; Pouquet *et al.* 2018)).

In a finite domain, an inverse cascade saturates at late times, forming a condensate in which the energy is concentrated in the largest scales. This condensation has been extensively studied in 2-D turbulence (see Hossain *et al.* 1983; Smith & Yakhot 1993, 1994; Chertkov *et al.* 2007). In quasi-2D systems it has been observed in rapidly rotating convection (Rubio *et al.* 2014; Favier *et al.* 2019), rotating turbulence (Seshasayanan & Alexakis 2018; Alexakis 2015; Yokoyama & Takaoka 2017) and thin-layer turbulence (Xia *et al.* 2011; van Kan & Alexakis 2019). In many of these cases, the amplitude of the condensate state (measured by the energy in the large scales) has been shown to vary discontinuously with the system parameters. Furthermore, close to the transition, bistability has been observed: the system was either attracted or not to the condensate state depending on the initial conditions. In particular in thin-layer flows, for values of  $H$  close to  $H_c$ , the system was attracted to either a 2-D condensate state (where most of the energy is concentrated in two counter-rotating, large-scale, 2-D vortices) or a 3-D turbulent state (where energy is mostly contained in 3-D small scale fluctuations) (van Kan & Alexakis 2019). The bistability in this system was accompanied by sudden ‘jumps’ between these two states. These transitions occur randomly with the waiting times that are, presumably, stochastic, following a statistical distribution that characterises the bistable regime.

In this paper, we present the first analysis of the statistical properties of thin-layer turbulence close to the critical height. We use a very large number of direct numerical simulations (DNS) and calculate the probability distribution functions (PDFs) of the transition times: the *decay time*  $\tau_d$  from a 2-D condensate state to a 3-D turbulent state and the *build-up time*  $\tau_b$  from a 3-D turbulent state to a 2-D condensate state. We examine their dependence to  $H$  and attempt to model the transitions in terms of a particle in a one dimensional potential using a Langevin equation.

## 2. Setup and results from direct numerical simulations

In this study, we consider forced incompressible 3-D flow in a triply periodic domain of dimensions  $L \times L \times H$  with  $H \ll L$ . The setup is identical with the one studied in (van Kan & Alexakis 2019). The thin direction is referred to as the *vertical* ‘ $z$ ’ direction and the remaining two as the *horizontal* ‘ $x, y$ ’ directions. The flow obeys the incompressible Navier-Stokes equation

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla P + \nu \nabla^2 \mathbf{v} + \mathbf{f}, \quad (2.1a)$$

$$\nabla \cdot \mathbf{v} = 0, \quad (2.1b)$$

where  $\mathbf{v}(\mathbf{x}, t)$  is the velocity field,  $P(\mathbf{x}, t)$  is physical pressure divided by constant density,  $\nu$  is kinematic viscosity and  $\mathbf{f}$  is the external body force injecting energy into the flow. In this work, we use two different forcing functions: stochastic  $\mathbf{f}_s$  and deterministic  $\mathbf{f}_d$ . Both forcing functions depend only on  $x$  and  $y$  and have only  $x$  and  $y$  components, *i.e.*, are two-dimensional-two-component (2D2C) fields. In both cases, the force is divergence-free and only acts on a shell of wavenumbers  $|\mathbf{k}| = k_f = 2\pi/\ell$ . The stochastic force is delta-correlated in time, which leads on average to a fixed mean injection rate  $\langle \mathbf{v} \cdot \mathbf{f}_s \rangle = \epsilon$ .

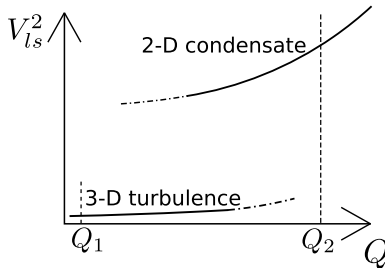


Figure 1: Sketch illustrating a hysteresis loop close to the critical height. Solid and dash-dotted lines represent the stable and unstable branches. We select initial conditions for *decay* and *build-up* experiments from the typical configurations at sufficiently small and large values of  $Q$  (here denoted by  $Q_1$  and  $Q_2$ ), respectively.

The deterministic force  $\mathbf{f}_d$  is written in terms of the the Fourier transform of the velocity field,  $\hat{\mathbf{v}}(\mathbf{k})$ , as

$$\mathbf{f}_d(\mathbf{x}, t) = \epsilon \sum_{|\mathbf{k}|=k_f} \frac{\hat{\mathbf{v}}(\mathbf{k})e^{i\mathbf{k}\cdot\mathbf{x}}}{\sum_{|\mathbf{k}'|=k_f} |\hat{\mathbf{v}}(\mathbf{k}')|^2} + i(\epsilon k_f^2)^{1/3} \sum_{|\mathbf{k}_h|=k_f} \Omega_{\mathbf{k}_h} \hat{\mathbf{v}}_{2D}(\mathbf{k}_h) e^{i\mathbf{k}_h\cdot\mathbf{x}}, \quad (2.2)$$

where the sum is taken over all modes with  $k_z = 0$  and  $|\mathbf{k}| = k_f$ , and  $\Omega_{\mathbf{k}_h}$  are time-independent random numbers that are uniformly distributed over  $[-1, 1]$ . They are kept fixed throughout the simulation time and are the same for all simulations. Since  $\Omega_{\mathbf{k}_h}$  is time-independent, the forcing is indeed deterministic, i.e. is fully determined by the velocity field at any time. The energy injection rate of  $\mathbf{f}_d$  at every instant is  $\epsilon$ , matching the mean injection rate of  $\mathbf{f}_s$ .

For both forcing functions, the system is characterised by three non-dimensional parameters: the injection scale Reynolds number  $Re = (\epsilon \ell^4)^{1/3} / \nu$ , the ratio between forcing scale and box height  $Q = \ell / H$ , and the ratio between forcing scale and the horizontal domain size  $K = \ell / L$ . In all simulations, we focus on the horizontal large-scale kinetic energy, defined as

$$V_{ls}^2 = \sum_{\substack{\mathbf{k}, k_z=0 \\ |\mathbf{k}| < k_{max}}} [|\hat{v}_x(\mathbf{k})|^2 + |\hat{v}_y(\mathbf{k})|^2], \quad (2.3)$$

where  $k_{max} = \sqrt{2\pi/L}$ . The simulations performed for this work use an adapted version of the Geophysical High-Order Suite for Turbulence (GHOST) which uses pseudo-spectral methods including 2/3 de-aliasing to solve for the flow in the triply periodic domain, (see Mininni *et al.* 2011). For all experiments, we fix  $K = 1/8$  and  $Re = 203$  at a resolution of  $128 \times 128 \times 16$ , varying  $Q$  over the interval  $[1.6, 2.0]$ . We choose these low resolution and  $Re$  because very long-duration runs are needed for this study. In addition, we also made runs at a resolution  $256 \times 256 \times 16$  at  $Re = 406$ , which qualitatively showed the same dynamics, even though reliable statistical analysis was not done in this case due to longer CPU times required to integrate (2.1).

Depending on  $Q$  and the initial conditions, the system is attracted either to the 2-D condensate state or the 3-D turbulent state as sketched in the  $V_{ls} - Q$  plane in figure 1. The upper branch corresponds to the 2-D condensate state while the lower branch corresponds to the 3-D turbulent state. The dash-dotted lines indicate regions where jumps from one state to the other are observed. As detailed below, we perform *decay* and *build-up* experiments for each value of  $Q$ . In the build-up experiments, initial conditions

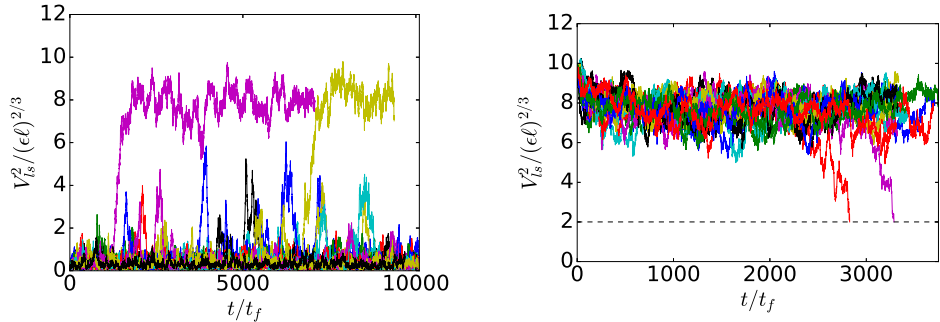


Figure 2: Typical time-series of  $V_{ls}^2$  for build-up experiments ( $Q = 1.55$ , left) and decay ( $Q = 1.556$ , right) experiments ( $\mathbf{f} = \mathbf{f}_s$ ). We define a build-up time  $\tau_b$  (or a decay time  $\tau_d$ ) as the time when  $V_{ls}^2$  grows (or drops) to its condensate mean value (or a small threshold  $\approx 2(\epsilon\ell)^{2/3}$ ). These  $\tau_b$  and  $\tau_d$  fluctuate and their statistics are of our interest.

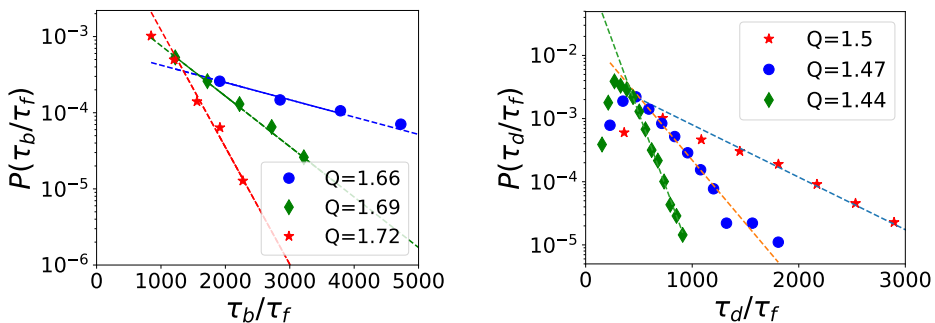


Figure 3: PDFs of the scaled build-up time  $\tau_b/\tau_f$  (left) and the scaled decay time  $\tau_d/\tau_f$  (right) for different values of  $Q$ , with  $\tau_f = (\ell^2/\epsilon)^{1/3}$ . The stochastic forcing  $\mathbf{f}_s$  is used. The PDFs have exponential tails whose characteristic time scale increases as the transition is approached.

corresponding to the 3-D turbulent state are used (see figure 1). In these simulations, we observe the build-up of 2-D condensates after a certain simulation time, which we denote by  $\tau_b$ . In the decay experiments, initial conditions corresponding to the 2-D condensate state are used. The system is evolved until the 2-D condensate decays. When decay or build-up events occur, the integration is interrupted and the next independent experiment is initiated. For the stochastic forcing, runs are started from a fixed initial condition but with different random number sequences, while for deterministic forcing, the initial conditions are altered by a small random perturbation that is different for every run. Figure 2 illustrates typical time-series for build-up and decay experiments. We note that similar procedures have been used to determine a critical Reynolds number for turbulent-laminar transitions in pipe flows (see Avila *et al.* 2011).

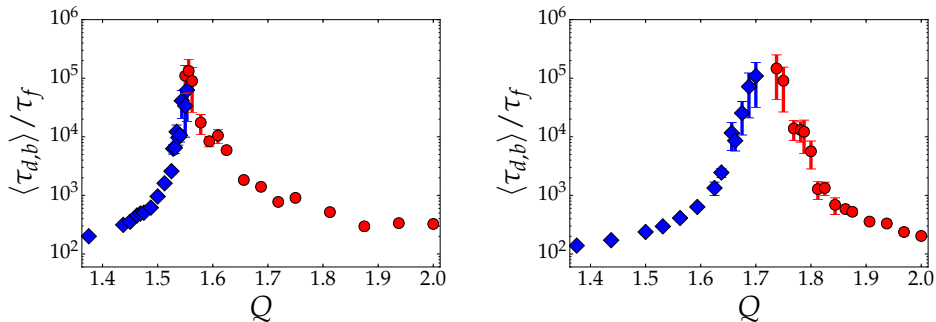


Figure 4: Mean transition times, non-dimensionalised by  $\tau_f = (\ell^2/\epsilon)^{1/3}$ , for stochastic (left) and deterministic (right) forcing as a function of  $Q$ . Blue diamonds correspond to  $\langle \tau_d \rangle$  in the decay experiments and red circles correspond to  $\langle \tau_b \rangle$  in the build-up experiments. Error bars are estimated based on the approximation that the PDF is exactly exponential.

### 3. Build-up and decay times

We measure the statistical properties of the decay and build-up times  $\tau_d, \tau_b$  by using more than 2.5 million CPU hours, which amount to ten million ( $10^7$ ) eddy turnover times in this system. Figure 3 shows PDFs of  $\tau_d$  and  $\tau_b$  for the stochastic forcing  $\mathbf{f}_s$  for different values of  $Q$ . All PDFs have an exponential tail, whose slope (in log-linear scale) increases as the transition is approached. The PDFs for the deterministic forcing  $\mathbf{f}_d$  show qualitatively the same results. An exponential PDF of waiting times implies that the waiting mechanism can be modeled using a memoryless process (Billingsley 2008). We explore this possibility in Section 4.

The resulting mean build-up and decay times,  $\langle \tau_b \rangle, \langle \tau_d \rangle$ , are shown in figure 4 for stochastic (left panel) and deterministic (right panel) forcing in log-linear coordinates. The ascending branch (left, in blue) represents the mean decay time  $\langle \tau_d \rangle$  and the descending branch (right, in red) represents the build-up time  $\langle \tau_b \rangle$ . For each case, both transition times increase drastically when a certain value of  $Q$  is approached. This increase is faster than exponential (super-exponential) and could be either diverging at some critical values  $Q_b$  and  $Q_d$  or staying finite (similar to what is observed for the decay and split time of turbulent puffs in pipe flows (Hof *et al.* 2006, 2008; Avila *et al.* 2011)). In the former case, the 2-D condensate is never formed below the critical value  $Q_b$  for which  $\langle \tau_b \rangle$  diverges, while above  $Q_d$  for which  $\langle \tau_d \rangle$  diverges, the 2-D condensate remains forever. In the latter case, a double-exponential function might be used to fit this super-exponential increase, supported by the argument using extreme value statistics (Fisher & Tippett 1928; Gumbel 1935; Goldenfeld *et al.* 2010; Goldenfeld & Shih 2017). This can be justified if we assume that the transition to the condensate state is triggered when the maximum value of the small scale vorticity exceeds a certain threshold value.

Four different scenarios may be envisaged for the  $Q$ -dependence of the transition times, illustrated in figure 5. In the first scenario, both  $\langle \tau_b \rangle$  and  $\langle \tau_d \rangle$  diverge at  $Q_b, Q_d$  with  $Q_d < Q_b$ . In the range  $(Q_d, Q_b)$ , where both transition times diverge, either the 3-D turbulent or 2-D condensate state is selected depending on initial conditions, towards which the system approaches. In the second scenario,  $\langle \tau_b \rangle$  and  $\langle \tau_d \rangle$  diverge at the same point, *i.e.*,  $Q_d = Q_b$ . This is an analogue of standard equilibrium phase transitions with a single power-law singularity. In the third scenario, a crossover is observed, *i.e.*,  $Q_b < Q_d$ ,

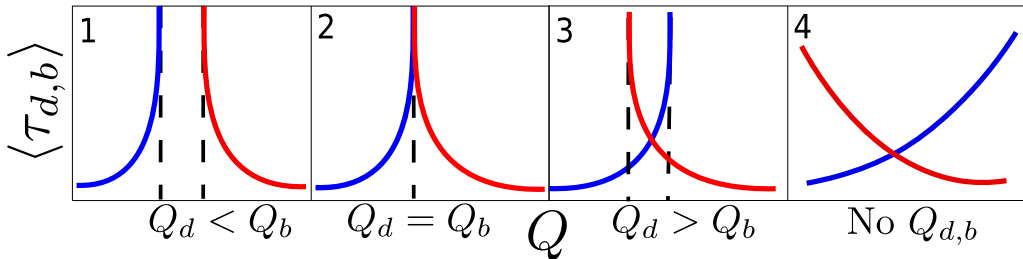


Figure 5: Four scenarios for dependence of transition times on  $Q$ . In each panel, the x-axis represents  $Q$  and the y-axis is either the mean decay time  $\langle \tau_d \rangle$  (left branch) or the mean build-up time  $\langle \tau_b \rangle$  (right branch). Dashed vertical lines indicate  $Q_{d,b}$ , where the mean transition times diverge.

where random transitions between the two states are possible within a finite range of  $Q$  between  $Q_b$  and  $Q_d$ . Finally, in the fourth scenario, a crossover is again observed, but without any divergence of  $\langle \tau_b \rangle$  and  $\langle \tau_d \rangle$  for finite  $Q$ . This scenario is compatible with the double-exponential fitting function explained above, where transitions between the two states are possible for all  $Q$  (although they are extremely rare). From the data in figure 4, we can see that for the stochastic forcing, the two branches are intersecting around  $Q = Q_s \approx 1.55$  at a value of around  $10^5$  eddy turnover times. Therefore we can exclude cases 1 and 2 for  $\mathbf{f}_s$ , while all four scenarios are possible for  $\mathbf{f}_d$ . In addition, it may be proven (see Gallet & Doering 2015) and has been confirmed numerically (van Kan & Alexakis 2019), that beyond a second critical value  $Q_{2D}$ , the flow two-dimensionalises and the condensate is stable to 3-D perturbations in the long-time limit. Therefore, condensate decay time diverges at least for  $Q > Q_{2D}$  and we can exclude a double-exponential behavior extending to all  $Q$  for  $\langle \tau_d \rangle$ . Note that based on our evidence, we cannot exclude that condensate build-up time never becomes infinite. In a future study, rare event algorithms may help elucidating these questions (see Section 5).

#### 4. Effective Markovian modelling

The exponential PDFs of the transition times (figure 3) indicate that these times are stochastically determined by a mechanism that is not affected by long-time correlations in the dynamics. Since the transitions are quantitatively characterized by a single macroscopic variable, the horizontal large-scale kinetic energy  $V_{ls}^2$  (figure 2), this observation implies that the dynamics of  $V_{ls}^2$  could be described by a Markov (memory-less) process, such as an inertia-less particle moving in a double-well potential in the presence of white noise. Within this effective description, the transitions are characterized as rare jumps of the particle between the two wells of the potential.

Motivated by this observation, in this section, we discuss to what extent the dynamics of  $E \equiv V_{ls}^2 / (\epsilon \ell)^{2/3}$  can be described by one-dimensional Markov process. Assuming the continuity of the trajectory of  $E(t)$ , a general form of this process is written as (Gardiner 1986):

$$\frac{dE}{dt} = -\frac{\partial U(E)}{\partial E} + \sqrt{2B(E)}\xi(t), \quad (4.1)$$

where  $\xi(t)$  is Gaussian white noise satisfying  $\langle \xi(t) \rangle = 0$  and  $\langle \xi(t)\xi(t') \rangle = \delta(t - t')$  and we use the Itô rule for the multiplication between  $\xi(t)$  and  $\sqrt{2B(E)}$ . The potential  $U(E)$  and the  $E$ -dependent diffusion constant  $B(E)$  characterise the dynamics and are

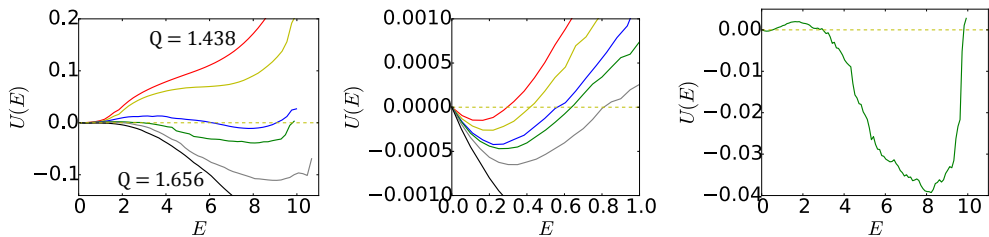


Figure 6: Left panel: The potential  $U(E)$  obtained from DNS (both decay and build-up experiments) for different values of  $Q$ . The values of  $Q$  from top to bottom are 1.438 (red), 1.5 (yellow), 1.556 (blue), 1.563 (green), 1.594 (grey), 1.656 (black). Middle panel: an enlarged view close to  $E = 0$ . Right panel: an enlarged view of  $U(E)$  for  $Q = 1.563$ . The potential is obtained using eq. A 2 for stochastic forcing.

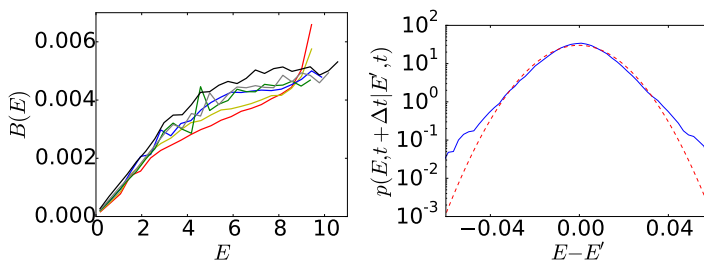


Figure 7: Left panel: The  $E$ -dependent diffusion constant  $B(E)$  obtained using eq. A 3 for stochastic forcing. Colors are as in Fig 6. Right panel: Transition probability  $p(E, t + \Delta t | E', t)$  obtained from DNS (blue solid line) and a Gaussian fit (red dashed line). We set  $E' = 0.5$  and  $\Delta t = 0.2$  with  $Q = 1.563$  for a stochastic forcing build-up experiment.

to be determined. Note that the noise term models the smaller-scale turbulent motions. Eq. (4.1) indicates that the average and the variance of  $dE/dt$  conditional on  $E$  are equal to  $-\partial U(E)/\partial E$  and  $B(E)/dt$  respectively. From the time-series data of the DNS, we thus evaluate these statistical properties and estimate  $U(E)$  and  $B(E)$  (see Appendix A for more detail). The results are shown in figures 6 and 7. When  $Q$  is well below the transition,  $U(E)$  has a single minimum at  $E \simeq 0.1$ . Positive slopes at larger values of  $E$  indicate a mean drift towards the 3-D turbulent state. As  $Q$  approaches the transition,  $U(E)$  becomes flatter, meaning that this drift vanishes, and a second minimum appears at  $E \simeq 7$  for  $Q \simeq 1.5$ . This indicates that the system is in a bistable regime. The second minimum becomes more dominant as  $Q$  is further increased. Eventually for  $Q \gtrsim 1.65$  the first minimum disappears and the system is left with a single minimum corresponding to the condensate state. In the presence of bistability, the time scale for the system to jump from one minimum to the other depends exponentially on the amplitude  $\Delta U$  of the potential barrier, *i.e.*,  $\tau \sim \exp[-\Delta U/B]$  (Gardiner 1986). An order-of-magnitude estimate shows that this is in agreement with the values of  $\langle \tau_a \rangle, \langle \tau_b \rangle$  measured in the previous section.

The interpretation of our results using a Langevin equation with a double-well potential is the simplest model to describe a discontinuous phase transition. The presence of a double-well potential implies that the system can always jump from one state to the other if one waits long enough. However we cannot conclude that  $\langle \tau_a \rangle$  and  $\langle \tau_b \rangle$  do not diverge for finite  $Q$  (Scenario 4 in figure 5) from this observation. First of all, the range

of  $Q$  that we have studied is highly limited. Second, an oversimplification has been made when we assumed that the system could be described by a single variable  $E$ , while the system in reality evolves in an extremely high-dimensional space. Indeed disagreements between the 1D model (4.1) and DNS results can be detected when we look at the distribution of the energy increment  $\Delta E$  over a small time interval  $\Delta t$ . According to the Langevin equation (4.1), this distribution needs to be Gaussian, but this is not exactly true for the DNS results: using the time-series data of DNS, we evaluate the transition probability  $p(E, t + \Delta t | E', t)$  from the state  $E'$  at time  $t$  to  $E$  at time  $t + \Delta t$ . In figure 7 we plot this probability with  $E' = 0.5$  and  $\Delta t = 0.2$  for stochastic forcing with  $Q = 1.5625$ , which shows deviations from a Gaussian distribution.

## 5. Conclusions

In this work we have studied the statistical properties of thin-layer flows close to the transition between a 3-D turbulent flow and the formation of a 2-D condensate. Such transitions have recently been discovered in a variety of systems (Seshasayanan & Alexakis 2018; Favier *et al.* 2019; van Kan & Alexakis 2019) and this work is the first attempt to systematically study their statistics. We have measured the probabilities of the transition times between the two states, where the mean transition times were shown to increase by three orders of magnitude by a relatively small change (10%) of the control parameter  $Q$ . We point out the qualitative similarity between figure 5 of (Avila *et al.* 2011) for the turbulent-laminar transitions in pipe flows and figure 4 of our work. Although the physical situations are different, in both cases we observe super-exponential growing time scales of two competing processes. Our results could neither exclude nor confirm whether this sharp increase has a double-exponential scaling form  $\exp(\beta \exp(\alpha x))$ , supported by an argument based on extreme value statistics (Goldenfeld *et al.* 2010). This leaves a possibility of the divergence of mean transition times, *i.e.*, transitions from one state to the other could become impossible for a certain range of  $Q$ .

Our results show that the system can be modeled to some extent as an inertia-less particle trapped in a one-dimensional potential in the presence of stochastic noise. The model revealed that close to the transition the potential displays two minima implying the existence of a bistable state. Discrepancies in the noise statistics of the DNS and of the stochastic model were observed that were attributed in the multi-dimensional nature of the real problem.

Several simplifying assumptions have been made in this work in order to make the problem more tractable. For example, the domain was triply periodic and also the forcing was 2-D. These simplifications could limit the applicability of these results to laboratory or natural flows. Further investigations with more realistic boundary conditions and forcing are thus necessary. More importantly, the present investigation was limited to a single relatively small value of  $Re$  and  $K$  (the scale separation between the forcing length scale and the horizontal domain scale). Examining the observed behavior at larger values of  $Re$  and  $K$  is crucial for validating the robustness of our results and for their applications to natural flows. Unfortunately, the extremely long duration of decay and build-up times close to the transitions limits the range of parameters that can be examined with DNS.

However, there are alternative methods that have been developed in the recent years that could address this problem. In particular, it could benefit from studies using rare event sampling algorithms, such as a method calculating instanton based on Freidlin-Wentzell theory (Chernykh & Stepanov 2001; Heymann & Vanden-Eijnden 2008; Grafke *et al.* 2015*b,a*; Grigorio *et al.* 2017), splitting methods that copy rare event realizations to efficiently accumulate statistics (Allen *et al.* 2005; Giardinà *et al.* 2006; C erou &



Guyader 2007; Tailleur & Kurchan 2007; Teo *et al.* 2016; Nemoto *et al.* 2016; Lestang *et al.* 2018; Bouchet *et al.* 2019) and also a recently proposed method that relies on feedback control of Reynolds number (Nemoto & Alexakis 2018). Such studies can help to overcome the difficulty caused by the extremely long computational time required to accurately describe the rare transition events close to the onset. Studies at larger  $Re$  or scale separations could therefore become tractable using these methods.

Furthermore given the large experimental literature (see Xia *et al.* 2011; Xia & Francois 2017) on the transition between 3-D turbulence and condensation in thin layers, it would be exciting and very important to study the observed bistability experimentally. The biggest advantage of an experiment compared to DNS would be that much longer observation times are possible as well as higher  $Re$ . The same remarks apply to rotating turbulence.

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## Appendix A. Determining $U(E)$ and $B(E)$

In this appendix we express  $U(E)$  and  $B(E)$  in terms of transition probabilities to obtain expressions which allow determining them from the DNS time series. For convenience, let  $A(E) \equiv -\frac{dU}{dE}$ , the drift velocity. For a small time increment  $\Delta t$ , we denote by  $p(E, t + \Delta t | E', t)$  the transition probability from  $E(t + \Delta t) = E$  at time  $t + \Delta t$  to  $E(t) = E'$  at time  $t$ . It obeys, (see Gardiner 1986),

$$p(E, t + \Delta t | E', t) - \delta(E - E') = -\frac{\partial}{\partial E} A(E) \delta(E - E') \Delta t + \frac{\partial^2}{\partial E^2} B(E) \delta(E - E') \Delta t + O(\Delta t^2) \quad (\text{A } 1)$$

By multiplying both sides by  $E - E'$  or  $(E - E')^2$  and integrating over  $E$ , we get

$$\int dE (E - E') p(E, t + \Delta t | E', t) = A(E') \Delta t + O(\Delta t^2), \quad (\text{A } 2)$$

$$\int dE (E - E')^2 p(E, t + dt | E', t) = 2B(E') \Delta t + O(\Delta t^2). \quad (\text{A } 3)$$

The left-hand sides (and thus  $A$  and  $B$ ) are measurable from a time-series  $E_{DNS}(t)$  of large-scale energy by computing the mean of  $E_{DNS}(t + \Delta t) - E_{DNS}(t)$  and  $(E_{DNS}(t + \Delta t) - E_{DNS}(t))^2$ , over all times  $t$  for which  $E_{DNS}(t) = E'$ , for all values of  $E'$ . Finally the potential  $U(E)$  is obtained from  $A(E)$  by simple integration.

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