

Rigorous Analysis of Random Linear Estimation - via spatial Coupling

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... coming back to our almost 10 year old work with Satish Korada - (Tight Bounds on the Capacity of Binary Input Random CDMA Systems – in Transactions Inf. Theory)

... independent analysis without spatial coupling of Henry Pfister and Gallen Reeves

PLAN

- I - Gaussian random linear estimation: setting
- II - Rigorous results on mutual information and MMSE (replica)
- III - Optimality range of Approximate Message Passing
- IV - Spatial coupling and comparison of thresholds
- V - Upper bound on mutual information by interpolation method
- VI - Exploiting sub-optimality of AMP: integration arguments
- VII - Conclusion, remarks

I. Gaussian random linear estimation: setting

Reconstruct a signal $\mathbf{s}_i \sim P_0(\cdot)$, $i = 1, \dots, N$ from M linear measurements

$$y_\mu = \sum_{i=1}^N \phi_{\mu i} \mathbf{s}_i + z_\mu \sqrt{\Delta}, \quad \mu \in \{1, \dots, M\}$$

Random measurement matrix $\phi_{\mu i} \sim \mathcal{N}(0, \frac{1}{N})$ and noise $z_\mu \sim \mathcal{N}(0, 1)$.

Set $\alpha = \frac{M}{N}$ for the measurement rate.

Find estimator $\hat{\mathbf{s}}(\mathbf{y})$ with a "good" $\text{MSE}[\hat{\mathbf{s}}(\cdot)] = \mathbb{E}\|\mathbf{s} - \hat{\mathbf{s}}(\mathbf{y})\|^2$. The optimal one is

$$\hat{\mathbf{s}}^{\text{MMSE}}(\mathbf{y}) = \mathbb{E}_{\mathbf{x}|\mathbf{y}}[\mathbf{x}|\mathbf{y}]$$

in other words

$$\underbrace{\mathbb{E}\|\mathbf{s} - \mathbb{E}_{\mathbf{x}|\mathbf{y}}[\mathbf{x}|\mathbf{y}]\|^2}_{\text{MMSE}} \leq \text{MSE}[\hat{\mathbf{s}}(\cdot)]$$

From the Bayes formula $P(\mathbf{x}|\mathbf{y}) = P(\mathbf{y}|\mathbf{x})P_0(\mathbf{x})/P(\mathbf{y})$:

$$P(\mathbf{x}|\mathbf{y}) = \frac{1}{\mathcal{Z}(\mathbf{y})} \exp\left(-\frac{1}{2\Delta} \sum_{\mu=1}^M ([\phi\mathbf{x}]_{\mu} - y_{\mu})^2\right) \prod_{i=1}^N P_0(x_i)$$

where the partition function is

$$\mathcal{Z}(\mathbf{y}) = \int \exp\left(-\frac{1}{2\Delta} \sum_{\mu=1}^M ([\phi\mathbf{x}]_{\mu} - y_{\mu})^2\right) \prod_{i=1}^N P_0(x_i) dx_i$$

So the MMSE estimator

$$\hat{\mathbf{s}}^{\text{MMSE}}(\mathbf{y}) = \mathbb{E}_{\mathbf{x}|\mathbf{y}}[\mathbf{x}|\mathbf{y}] = \langle \mathbf{x} \rangle$$

is a Gibbs average $\langle - \rangle$ with quenched disorder $\mathbf{y} \equiv \{\phi, \mathbf{s}, \mathbf{z}\}$.

Key objects.

Mutual information / free energy

$$i_N = \frac{1}{N} \mathbb{E}_{\phi} \mathbb{E}_{\mathbf{X}, \mathbf{Y}} \left[\ln \left(\frac{P(\mathbf{X}, \mathbf{Y})}{P_0(\mathbf{X})P(\mathbf{Y})} \right) \right] = -\frac{\alpha}{2} - \underbrace{\frac{1}{N} \mathbb{E}_{\phi, \mathbf{s}, \mathbf{z}} \ln(\mathcal{Z})}_{\text{average free energy}}$$

where

$$\mathcal{Z} = \int \exp \left(-\frac{1}{2\Delta} \sum_{\mu=1}^M ([\phi \mathbf{x}]_{\mu} - [\phi \mathbf{s}]_{\mu} - z_{\mu} \sqrt{\Delta})^2 \right) \prod_{i=1}^N P_0(x_i) dx_i$$

MMSE (per variable)

$$\text{mmse}_N = \frac{1}{N} \mathbb{E}_{\phi, \mathbf{s}, \mathbf{z}} \|\mathbf{s} - \langle \mathbf{x} \rangle\|^2$$

Measurement MMSE

$$\text{ymmse}_M = \frac{1}{M} \mathbb{E}_{\phi, \mathbf{s}, \mathbf{z}} \|\phi(\mathbf{s} - \langle \mathbf{x} \rangle)\|^2 = \underbrace{\frac{2}{\alpha} \frac{di_N}{d\Delta^{-1}}}_{\text{I-MMSE formula}}$$

II. The replica formula and rigorous results

Physics calculations (Kabashima - J. Phys. A 2003, Tanaka - Tran. Inf. Th. 2004) yield:

$$\lim_{N \rightarrow +\infty} i_N = \min_E i_{\text{RS}}(E; \Delta)$$

To describe i_{RS} introduce a scalar “denoising model”:

$$\tilde{y} = \tilde{s} + \tilde{z}\Sigma, \quad \tilde{z} \sim \mathcal{N}(0, 1)$$

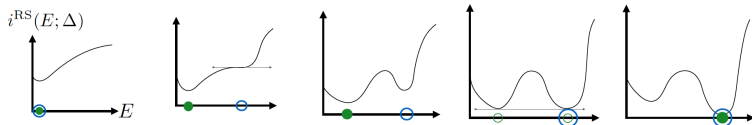
with averaged free energy or mutual information $I(\tilde{S}; \tilde{Y})$:

$$\tilde{f}(\Sigma) = -\mathbb{E}_{s,z} \ln \int dx P_0(x) \exp \left\{ -\frac{(\tilde{x} - (\tilde{s} + \tilde{z}\Sigma))^2}{2\Sigma^2} \right\}$$

Effective signal-to-noise ratio $\Sigma(E; \Delta)^{-2} = \alpha/(\Delta + E)$ and

$$i_{\text{RS}}(E; \Delta) = \frac{1}{2} \left(\alpha \ln(1 + E/\Delta) - \frac{E}{\Sigma(E; \Delta)^2} \right) + \tilde{f}(\Sigma(E; \Delta)) - \frac{1}{2}$$

Assumption 1: P_0 such that $i_{RS}(E; \Delta)$ has at most 3 stationary points.



Definition: Δ_{RS} is the unique value s.t $i_{RS}(E; \Delta)$ has 2 minimisers. It is the unique non-analyticity point of $\min_E i_{RS}(E; \Delta)$.

Assumption 2: P_0 is a discrete mass distribution.

Remark: assumptions 1 + 2 can be removed by working a bit harder. Or by asking Henry Pfister and Gallen Reeves (arXiv:1607.02524 [cs.IT]).

Theorem 1: the replica calculation gives correct results.

- ▶ For all Δ ,

$$\lim_{N \rightarrow +\infty} i_N = \min_E i_{\text{RS}}(E; \Delta)$$

- ▶ The mutual information $\lim_{N \rightarrow +\infty} i_N$ has a unique non-analyticity threshold equal to Δ_{RS} .
- ▶ For all $\Delta \neq \Delta_{\text{RS}}$

$$\lim_{N \rightarrow +\infty} \text{mmse}_N = \underset{E}{\text{argmin}} i_{\text{RS}}(E; \Delta) \equiv \tilde{E}(\Delta)$$

and

$$\lim_{M \rightarrow +\infty} \text{ymmse}_M = \frac{\tilde{E}(\Delta)}{1 + \tilde{E}(\Delta)/\Delta}$$

Slightly more general result by independent methods:

(Pfister, Reeves - ISIT 2016 - arXiv:1607.02524 [cs.IT])

Previous results:

- Case with no phase transitions rigorously (Montanari, Tse - ITW 2006).
- Upper bound for binary signals (Korada, Macris - Allerton 2007 - Trans. Inf.Th 2010).

The following theorem is proved independently (and essentially before) the replica formula.

Theorem 2: relations between mmse's

For any discrete prior P_0 and almost every Δ (there might be several phase transitions here)

$$\lim_{N \rightarrow +\infty} \text{ymmse}_N = \lim_{N \rightarrow +\infty} \frac{\text{mmse}_N}{1 + \text{mmse}_N / \Delta}$$

Proof methods: based on concentration of "overlap parameters".

- ▶ Concentration of the free energy (e.g. use Ledoux-Talagrand for Gaussian variables $\phi_{\mu i}$, Z_μ and McDiarmid for the signal s_i)

$$\mathbb{P}(\ln \mathcal{Z} - \mathbb{E}[\ln \mathcal{Z}] \geq \epsilon N) \leq e^{-c\epsilon^2 N}$$

- ▶ + "Nishimori" identities for Bayesian inference (with known prior).

III. Optimality range of Approximate Message Passing

Min-Sum equs on dense graph + quadratic approximation \Rightarrow AMP.

Algorithm updates estimates $\hat{\mathbf{s}}^{(t)}(\mathbf{y})$, $t \geq 0$, with initialisation $\hat{\mathbf{s}}^{(0)} = 0$.

Theorem (Bayati-Montanari 2011): *State Evolution tracks the square error* $E^{(t)} = \lim_{N \rightarrow +\infty} \frac{1}{N} \|\mathbf{s} - \hat{\mathbf{s}}^{(t)}\|^2$. *Almost surely:*

$$E^{(t+1)} = \text{mmse}(\Sigma(E^{(t)}; \Delta)^{-2}), \quad E^{(0)} = \mathbb{E}[\mathbf{s}_i^2]$$

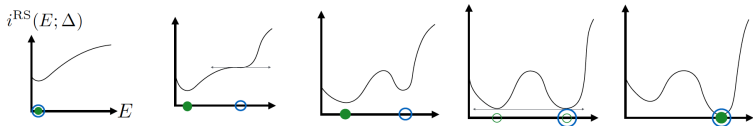
where $\text{mmse}(\Sigma^{-2})$ is associated to scalar channel $\tilde{y} = \tilde{s} + \tilde{z}\Sigma$,

$$\text{mmse}(\Sigma^{-2}) = \mathbb{E}[(\tilde{s} - \mathbb{E}[\tilde{x}|\tilde{y}])^2].$$

Recall: $\Sigma(E; \Delta)^{-2} = \alpha/(E + \Delta)$

Fixed point equation: $E = \text{mmse}(\Sigma(E; \Delta)^{-2}) \iff \frac{\partial}{\partial E} i_{\text{RS}}(E; \Delta) = 0$.

\Rightarrow state evolution is governed by the potential function $i_{\text{RS}}(E; \Delta)$:



- ▶ **easy phase** $\Delta < \Delta_{\text{AMP}}$: $E^{(\infty)} = \tilde{E}(\Delta)$ unique "good" min of i_{RS} .
- ▶ **hard phase** $\Delta \in [\Delta_{\text{AMP}}, \Delta_{\text{RS}}]$: $E^{(\infty)} > \tilde{E}(\Delta)$ stuck in local min.
- ▶ **bad phase** $\Delta > \Delta_{\text{RS}}$: $E^{(\infty)} = \tilde{E}(\Delta)$ global "bad" min of i_{RS} .

Recall $\tilde{E}(\Delta) = \underset{E}{\operatorname{argmin}} i_{\text{RS}}(E; \Delta)$.

Theorem: optimality range of AMP.

For $\Delta < \Delta_{\text{AMP}}$ (easy phase) and $\Delta > \Delta_{\text{RS}}$ (bad phase) AMP is optimal in the sense:

$$E^\infty = \lim_{t \rightarrow +\infty} E^{(t)} = \lim_{N \rightarrow \infty} \text{mmse}_N$$
$$\lim_{t \rightarrow +\infty} \text{ymse}_{\text{AMP}}^{(t)} = \lim_{M \rightarrow \infty} \text{ymmse}_M$$

Recall:

$$E^{(t)} = \lim_{N \rightarrow +\infty} \frac{1}{N} \|\mathbf{s} - \widehat{\mathbf{s}}^{(t)}\|^2, \quad \text{mmse}_N = \frac{1}{N} \mathbb{E} \|\mathbf{s} - \langle \mathbf{x} \rangle\|^2$$

and:

$$\text{ymse}_{\text{AMP}}^{(t)} = \lim_{N \rightarrow +\infty} \frac{1}{M} \|\phi(\mathbf{s} - \widehat{\mathbf{s}}^{(t)})\|^2, \quad \text{ymmse}_M = \frac{1}{M} \mathbb{E} \|\phi(\mathbf{s} - \langle \mathbf{x} \rangle)\|^2$$

Proof strategy

First define the static phase transition threshold as:

$$\Delta_{\text{Opt}} = \sup\{\Delta \text{ s.t. } \lim_{N \rightarrow +\infty} i_N \text{ is analytic in }]0, \Delta[\}$$

Main steps:

- 1- Prove that $\Delta_{\text{RS}} \leq \Delta_{\text{Opt}}$. Via a detour: **spatial coupling**.
- 2- Guerra-Tonninelli interpolation type upper bound on the mutual information (S.Korada-N.M 2010 for binary signals)

$$\lim_{N \rightarrow +\infty} i_N \leq \min_E i_{\text{RS}}(E; \Delta)$$

- 3- Sub-optimality of AMP:

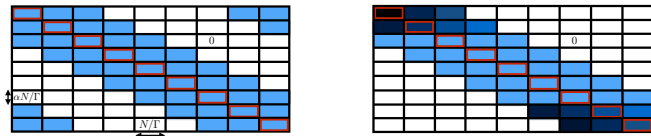
$$E^\infty \geq \limsup_{N \rightarrow \infty} \text{mmse}_N$$

- 4- By integration and analyticity arguments:

$$(1) + (3) + (2) \text{ imply } \lim_{N \rightarrow +\infty} i_N = \min_E i_{\text{RS}}(E; \Delta).$$

IV. Spatial coupling and the proof of $\Delta_{RS} \leq \Delta_{Opt}$

Random linear estimation problem with structured measurement matrix (in CS by Krzakala, Mézard, Sausset, Sun, Zdeborova).



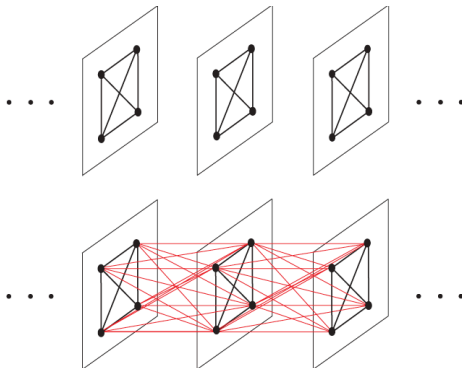
$\mathbb{R}^{M \times N}$ matrix made of $\Gamma \times \Gamma$ blocks (r, c) each with N/Γ columns and M/Γ rows. The i.i.d entries in block (r, c) are $\mathcal{N}(0, \frac{J_{r,c}}{N/\Gamma})$.

Periodic model (left): w forward and w backward *coupling blocks* with $J_{r,c} = \frac{1}{2w+1}$ if $|r-c| \leq w$.

Open model (right): at the boundaries the periodicity is broken. The boundaries are "seeded", e.g. the signal is known for the first few blocks.

Alternate view:

Chain of length Γ with dense graphs, each with N/Γ nodes, positioned at $c \in \{1, \dots, \Gamma\}$ and coupled to neighboring graphs $\{c-w, \dots, c+w\}$.



$$\sum_{\mu=1}^M ([\phi \mathbf{x}]_{\mu} - y_{\mu})^2 = \sum_{|c-c'| \leq w} \sum_{i \in c, j \in c'} [\phi^T \phi]_{ij} x_i x_j + \dots$$

Spatially coupled systems have two crucial properties:

- ▶ **Invariance**: The phase transition threshold is the same as the one of the uncoupled underlying system.
- ▶ **Threshold saturation**: The AMP threshold equals Δ_{RS} . With "seeded" boundary condition: no more metastable states. This is algorithmically favourable.

This is very generic: sparse graphical codes (LDPC), sparse superposition codes, compressed sensing, constraint satisfaction (to some extent), spiked Wigner model (matrix factorisation), spatially coupled Curie-Weiss models...

Theorem: Invariance of the mutual information

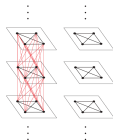
For fixed Γ and w : $\lim_{N \rightarrow \infty} i_{\Gamma, w}^{\text{per}} = \lim_{N \rightarrow \infty} i_N$.

For fixed w : $\lim_{\Gamma \rightarrow \infty} \lim_{N \rightarrow \infty} i_{\Gamma, w}^{\text{open}} = \lim_{N \rightarrow \infty} i_N$.

Corollary: $\Delta_{\text{Opt}}^{\text{coupled}} = \Delta_{\text{Opt}}$

Proof idea: new interpolation method connecting decoupled $w = 0$, spatially coupled $0 < w < (\Gamma - 1)/2$ and fully coupled $w = (\Gamma - 1)/2$ systems:

$$\lim_{N \rightarrow \infty} i_{\Gamma, (\Gamma-1)/2}^{\text{per}} \leq \lim_{N \rightarrow \infty} i_{\Gamma, w}^{\text{per}} \leq \lim_{N \rightarrow \infty} i_{\Gamma, 0}^{\text{per}}$$



(methodology is related to Jean's talk)

State evolution for the spatially coupled system:

Profile of MSE for positions $r = 1, \dots, \Gamma$:

$$E_r^{(t)} = \lim_{N \rightarrow \infty} \frac{1}{(2w+1)N/\Gamma} \sum_{c=r-w}^{r+w} \|\mathbf{s}_c - \widehat{\mathbf{s}}_c^{(t)}\|^2$$

Boundary seed: imposes $E_r^{(t)} = 0$ for all times if $r \in \mathcal{B}$.

For $r \notin \mathcal{B}$: recursive SE equation for the whole profile $(E_r^{(t)})_{r=1}^{\Gamma}$.

Initialization $E_r^{(0)} = \mathbb{E}[s^2]$.

Definition:

$$\Delta_{\text{AMP}}^{\text{coupled}} = \liminf_{w \rightarrow \infty} \liminf_{\Gamma \rightarrow \infty} \sup\{\Delta > 0 \mid E_r^{(\infty)} \leq E_{\text{good}}(\Delta) \forall r = 1, \dots, \Gamma\}$$

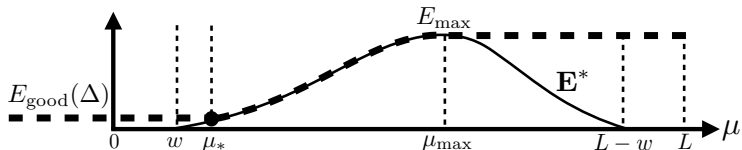
where $E_{\text{good}}(\Delta)$ the smallest minimum of $i_{\text{RS}}(E; \Delta)$.

Theorem - threshold saturation:

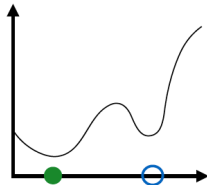
$$\Delta_{\text{AMP}}^{\text{coupled}} = \Delta_{\text{RS}}$$

Rough idea of proof: analyse a nucleation phenomenon

- ▶ Profile is driven to flat E_{good} for all positions $r \in \{1, \dots, \Gamma\}$ because it is energetically favourable to grow the seed.
- ▶ A reconstruction "wave" develops:



- ▶ The front of the wave is a "ball" rolling in the convex envelope of the potential as long as $\Delta < \Delta_{\text{RS}}$. $\Rightarrow \Delta_{\text{AMP}}^{\text{coupled}} = \Delta_{\text{RS}}$.



End of proof of $\Delta_{RS} \leq \Delta_{Opt}$:

$$\Delta_{RS} \stackrel{(a)}{=} \Delta_{AMP}^{\text{coupled}} \stackrel{(b)}{\leq} \Delta_{Opt}^{\text{coupled}} \stackrel{(c)}{=} \Delta_{Opt} \quad (\stackrel{(d)}{\leq} \Delta_{RS})$$

- ▶ (a) threshold saturation.
- ▶ (b) sub-optimality of AMP.
- ▶ (c) invariance of mutual information under coupling.

- ▶ (d) needs extra arguments using interpolation upper bound.

V. Upper bound by the interpolation method

Theorem: For any discrete prior P_0 we have

$$\lim_{N \rightarrow +\infty} i_N \leq \min_E i_{RS}(E; \Delta)$$

Proof sketch: non-linear interpolation between the denoising model at $t = 0$ and original system at $t = 1$.

$$\left\{ \begin{array}{l} \mathbf{y} = \phi \mathbf{s} + \mathbf{z} \frac{1}{\sqrt{\gamma(t)}}, \quad \gamma(0) = 0, \quad \gamma(1) = 1/\Delta \\ \tilde{\mathbf{y}} = \mathbf{s} + \tilde{\mathbf{z}} \frac{1}{\sqrt{\lambda(t)}}, \quad \lambda(0) = \underbrace{\Sigma(E; \Delta)^{-2}}_{\frac{\alpha}{\Delta + E}}, \quad \lambda(1) = 0 \end{array} \right.$$

Total "effective SNR" should be conserved for all t :

$$\frac{\alpha}{\gamma(t)^{-1} + E} + \lambda(t) = \frac{\alpha}{\Delta + E}$$

This induces an interpolation of mutual informations for $t \in [0, 1]$:

$$i_N(t=1) = i_N(t=0) + \int_0^1 dt \frac{di_N(t)}{dt}$$

$$i_N = i_{\text{RS}}(E; \Delta) + \int_0^1 dt \underbrace{\left\{ \frac{di_N}{dt} - \frac{\alpha}{2} \frac{d\gamma(t)}{dt} \left(\frac{E}{1 + E\gamma(t)} - \frac{E}{(1 + E\gamma(t))^2} \right) \right\}}_{\mathcal{A}_N + \mathcal{B}_N}$$

Using Gaussian integrations by parts:

$$\mathcal{A}_N = \frac{d\gamma(t)}{dt} \frac{1}{2N} \sum_{\mu=1}^M \mathbb{E}[(\langle \Phi(\mathbf{x}) \rangle_t)_\mu - (\Phi \mathbf{s})_\mu]^2 = \underbrace{\frac{\alpha}{2} \frac{d\gamma(t)}{dt}}_{\text{ymmse}_{N,t}}$$

(concentration of free energy and overlaps) $\approx \frac{\alpha}{2} \frac{d\gamma(t)}{dt} \frac{\text{mmse}_{N,t}}{1 + \text{mmse}_{N,t}/\Delta}$

$$\begin{aligned} \mathcal{B}_N &= \frac{d\lambda(t)}{dt} \frac{1}{2N} \sum_{i=1}^N \mathbb{E}[(\langle x_i \rangle_t - s_i)^2] = \underbrace{\frac{1}{2} \frac{d\lambda(t)}{dt}}_{\text{mmse}_{N,t}} \\ &= -\frac{\alpha}{2} \frac{d\gamma(t)}{dt} \frac{\text{mmse}_{N,t}}{(1 + E\gamma(t))^2} \end{aligned}$$

Finally:

$$i_N \approx i_{\text{RS}}(E; \Delta) - \frac{\alpha}{2} \int_0^1 dt \underbrace{\frac{d\gamma(t)}{dt} \frac{\gamma(t)(E - \text{mmse}_{N,t})^2}{(1 + E\gamma(t))^2(1 + \text{mmse}_{N,t}\gamma(t))}}_{\text{positive}}$$

which implies

$$i_N \leq \min_E i_{\text{RS}}(E; \Delta).$$

VI. Exploiting sub-optimality of AMP - integration argument and proof completion

We showed $\Delta_{RS} \leq \Delta_{\text{Opt}}$ (by spatial coupling)
and $i_N \leq \min_E i_{RS}(E; \Delta)$ (by interpolation).

Now use sub-optimality of AMP: $E^\infty \geq \limsup \text{mmse}_N \Rightarrow$

$$\underbrace{\limsup_{M \rightarrow +\infty} \text{ymmse}_M}_{\limsup_{N \rightarrow +\infty} \frac{di_N}{d\Delta^{-1}}} = \limsup_{N \rightarrow +\infty} \frac{\text{mmse}_N}{1 + \text{mmse}_N/\Delta} \leq \underbrace{\frac{E^{(\infty)}}{1 + E^{(\infty)}/\Delta}}_{\frac{\partial i_{RS}(E^\infty; \Delta)}{\partial \Delta^{-1}}}$$

Easy phase $\Delta < \Delta_{\text{AMP}}$:

$$E^\infty = \text{argmin} i_{RS}(E; \Delta) \quad \text{so} \quad \liminf_{M \rightarrow +\infty} \frac{di_N}{d\Delta} \geq \frac{d}{d\Delta} \min i_{RS}(E; \Delta).$$

Integrating over $[0, \Delta] \subset [0, \Delta_{\text{AMP}}]$: $\liminf_{N \rightarrow +\infty} i_N \geq \min_E i_{RS}(E; \Delta)$ thus

$$\lim_{N \rightarrow +\infty} i_N = \min_E i_{RS}(E^\infty; \Delta) \quad \text{for} \quad \Delta < \Delta_{\text{AMP}}$$

Interval $\Delta_{\text{AMP}} < \Delta < \Delta_{\text{Opt}}$: We know $\underbrace{\Delta_{\text{AMP}} \leq \Delta_{\text{RS}} \leq \Delta_{\text{Opt}}}_{\text{hard phase}}$.

- ▶ By unicity of analytic continuation: $\lim_{N \rightarrow \infty} i_N = \min_E i_{\text{RS}}(E; \Delta)$ for $\Delta < \Delta_{\text{RS}}$ and by concavity we have continuity so equality at Δ_{RS} .
- ▶ For $\underbrace{\Delta_{\text{RS}} \leq \Delta \leq \Delta_{\text{Opt}}}_{\text{"non-existent interval"}}$: Repeat the integration argument.

$$\int_{\Delta_{\text{RS}}}^{\Delta} d\Delta \frac{d}{d\Delta} \min_E i_{\text{RS}}(E; \Delta) \leq \liminf_{N \rightarrow +\infty} \frac{1}{N} \int_{\Delta_{\text{RS}}}^{\Delta} d\Delta \frac{d i_N}{d\Delta}.$$

which leads again to

$$\min_E i_{\text{RS}}(E; \Delta) \leq \liminf_{N \rightarrow +\infty} i_N$$

and to equality for $\Delta \in [0, \Delta_{\text{Opt}}]$ and also $\Delta_{\text{RS}} = \Delta_{\text{Opt}}$.

Summarizing $\lim_{N \rightarrow \infty} i_N = \min_E i_{\text{RS}}(E; \Delta)$ for $\Delta \leq \Delta_{\text{Opt}} = \Delta_{\text{RS}}$.

Bad phase: $\Delta > \Delta_{RS} = \Delta_{Opt}$

Use again an integration of

$$\int_{\Delta_{RS}}^{\Delta} d\Delta \frac{d}{d\Delta} \min_E i_{RS}(E; \Delta) \leq \liminf_{N \rightarrow +\infty} \frac{1}{N} \int_{\Delta_{RS}}^{\Delta} d\Delta \frac{di_N}{d\Delta}.$$

and combine with the interpolation bound.

Remark:

the integration argument does not work directly for $\Delta \in [\Delta_{AMP}, \Delta_{RS}]$

$$\underbrace{\frac{\partial i_{RS}(E^\infty; \Delta)}{\partial \Delta^{-1}}}_{\neq \frac{d}{d\Delta^{-1}} \min_E i_{RS}(E; \Delta)} \geq \limsup_{N \rightarrow +\infty} \frac{1}{N} \frac{di_N}{d\Delta^{-1}}$$

VII. Conclusion

- ▶ Similar analysis works for other Bayesian inference problems, e.g., LDPC codes, low-rank matrix factorisation, etc...
- ▶ Method is pretty generic except for the interpolation upper bound.
- ▶ New methods have appeared which don't use spatial coupling: see other talks today.